



## Easydic Series Shaft Incremental Encoder EV28



### Description

Small economical shaft encoder EV28 is widely used in light industries where space for sensor installation is a concern. The resolution is up to 600, and with its small size, light weight, and high precision, if fully meets the controlling requirements of the modern light industries. With the different shaft lengths available, the product can be use d in a wide variety of industrial environments. It's one of the most recommended choices when in consideration of performance and cost.

#### Features

Flexible coupling connection avoids damage to the encoder

•Stainless steel shaft  $\Phi 4$ ,  $\Phi 5$  ensures high stability and protection

•Metal housing for better shock resistance

- Protection class IP50
- Reverse connection protection
- Short circuit protection
- ·Cable output, waterproof rubber end

#### Mechanical Characteristics

Shaft diameter (mm)	Ф4/Ф5g6
Protection acc. to EN 60529	IP50
Speed	6000, continuous
Max load capacity of the shaft	5Naxial, 10Nradial
Shock resistance	30G/11ms
Vibration resistance	6G 10~2000HZ
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	approx.0.7×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.01Nm
Body material	AL-alloy UNI9002-5
Housing material	AL-alloy UNI9002-5
Operating temperature	-20~+80°C
Storage temperature	-30~+85°C
Weight	100g

Resolution: 50,100,200,300,360,500,600

### **Electrical Characteristics**

Output circuit	Push-pull	RS422	RS422
Resolution	Max. 600ppr	Max. 600ppr	Max. 600ppr
Supply voltage(VDC)	10-30V/5-30V	5V	10-30V
Power consumption (no load)	≤125mA	≤80mA	≤80mA
Permissible load (channel)	±80mA	±50mA	±50mA
Pulse frequency	Max. 300kHz	Max. 300kHz	Max. 300kHz
Signal level high	Min.Ub-1.5V	Min.3.4V	Min.3.4V
Signal level low	Max.0.8V	Max.0.4V	Max.0.4V
Rise time Tr	Max 1µs	Max 200ns	Max 200ns
Fall time Tr	Max 1µs	Max 200ns	Max 200ns

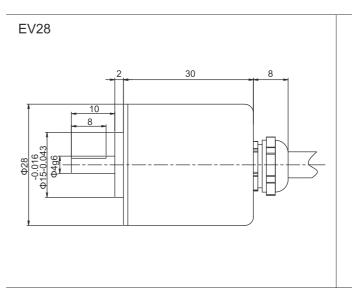
#### Terminal Assignment

Signal	0V	+U <sub>b</sub>	А	Ā	В	B	Z	Ī	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	÷

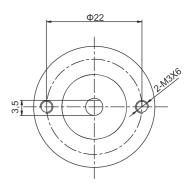
### Encoder

## Easydic Series Shaft Incremental Encoder EV28

#### Dimensions

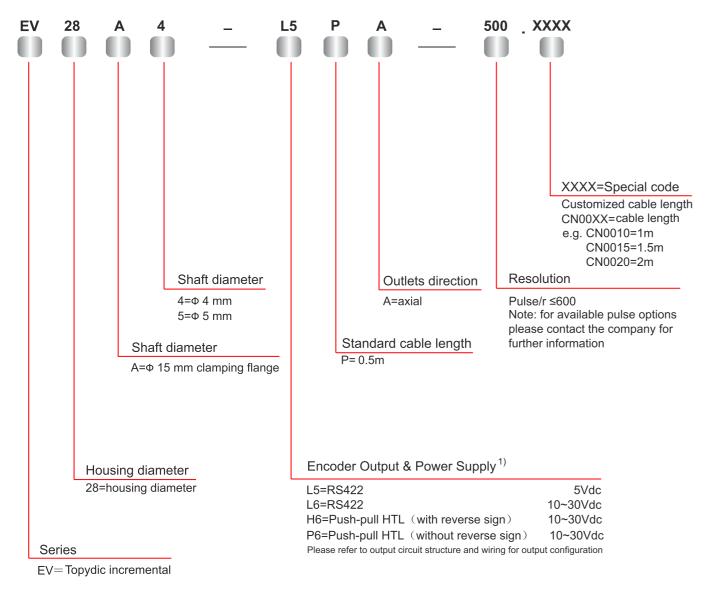






### Easydic Series Shaft Incremental Encoder EV28

Order Code



1)When UB=5V, short-circuit to channel, 0V, or+UB is permitted; When UB is greater than 5V, short-circuit to channel or 0V is permitted

## Topydic Small Shaft Incremental Encoder EV40A

#### Descriptions

Topydic series small shaft incremental encoder-EV40A delivers oustanding performance in mechanical shock-resistance and is capable of withstanding higher axial and radial loads so as to meet variousindustrial environments. Its special position of cabling fits to the limited installation sapce. Combining advanced signal processing technology with multiple types of electrical output, EV40A are capable of matching various upper control computers.

#### Features

- Stainless steel shaft ensures safety and stability in operation
- Metal casting housing for greater shock resistance
- Side cabling design greatly saves the installation space and simplifies wiring

### Mechanical Characteristics

	<b>A</b> 0-0
Shaft diameter (mm)	Φ6g6
Protection grade	IP66 standard, IP67 optional
Max. speed/minute	6000
Max. load capacity of the shaft	60N axial
	100N radial
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000HZ
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	1.9×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.08Nm
Body material	Al-alloy
Housing material	Zn-alloy
Operating temperature	-20~+85°C
Storage temperature	-25~+100°C
Weight	110g

Regular resolution: 10, 20, 30, 40, 50, 60, 70, 80, 90, 100, 200, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 2000, 4000, 2500, 5000, 2048

Note: Bold part is normally in stock. Other resolution are available only upon request.

### **Electrical Characteristics**

Output circuit	RS422	Push-pull	
Resolution	Max.5000ppr	Max.5000ppr	
Supply voltage(VDC)	5±0.25 or 10-30	10-30	
Power consumption(no load)	≤80mA	≤125mA	
Permissible load(channel)	±50mA	±80mA	
Pulse frequency	Max.800kHz	Max. 800kHz	
Signal level high	Min. 3.4V	Min.Ub-1.8	
Signal level low	Max. 0.4V	Max. 2.0V	
Rise time Tr	Max. 200ns	Max 1µs	
Fall time Tf	Max. 200ns	Max 1µs	





- Optional types of flange connection offers more flexibility
- Rerverse connection protection; short circuit protection

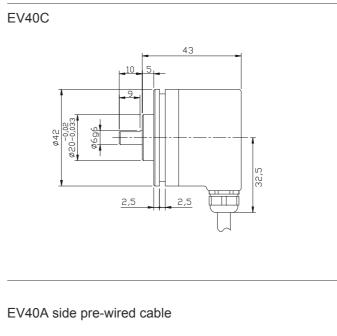
## Topydic Small Shaft Incremental Encoder EV40A

## Terminal Configuration

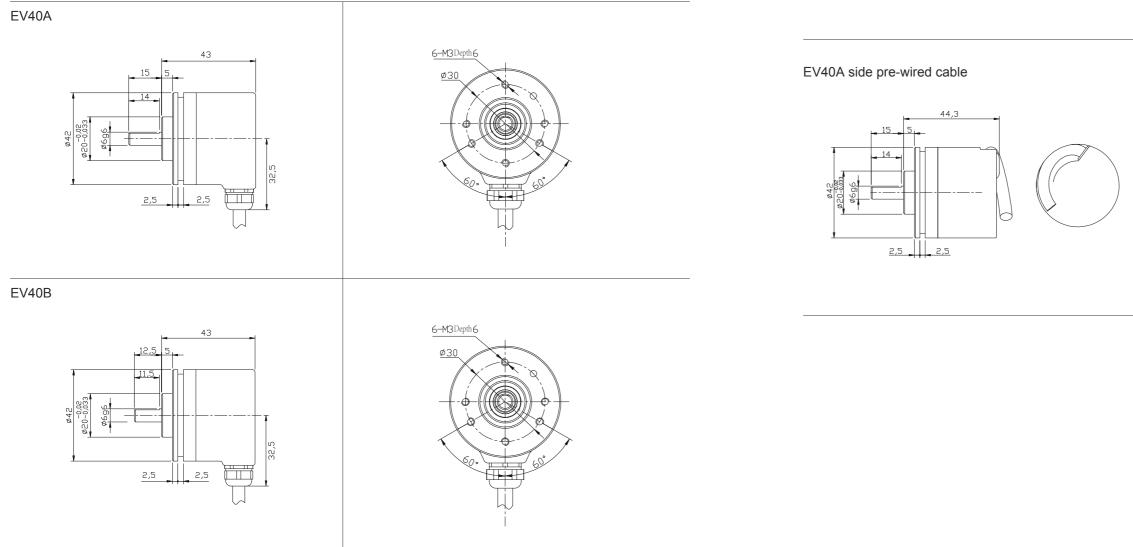
Signal	0V	+Ub	А	Ā	В	B	Z	Z	0V Sen	+Ub Sen	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	GY/PK	RD/BU	÷
Pin	10	12	5	6	8	1	3	4	11	2	PH

## Topydic Small Shaft Incremental Encoder EV40A

## Dimensions

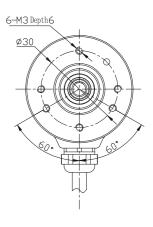


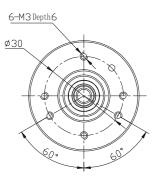
### Dimensions





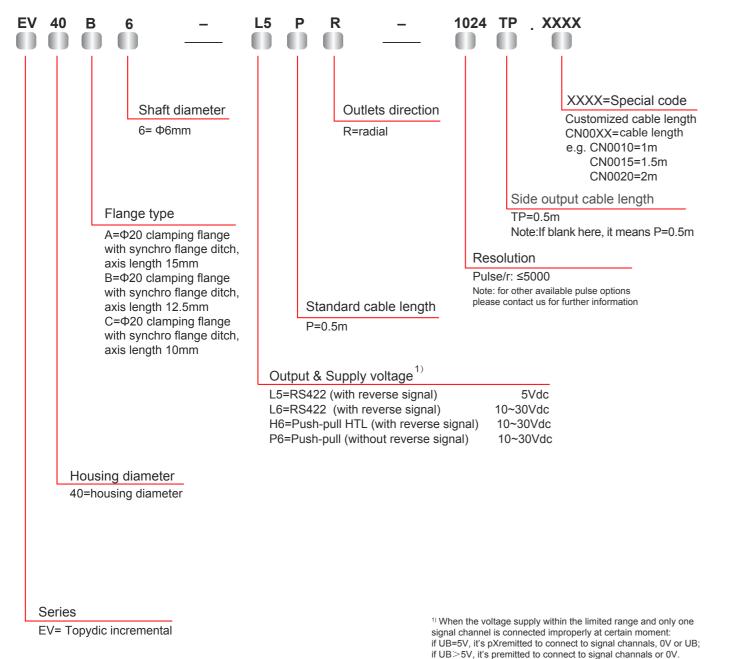






## Topydic Small Shaft Incremental Encoder EV40A

Order Code:



## Topydic Small Hollow Shaft Incremental Encoder EV40P

#### Descriptions

Topydic series small shaft incremental encoder-EV40P delivers oustanding performance in mechanical shock-resistance and is capable of withstanding higher axial and radial loads so as to meet variousindustrial environments. Its special position of cabling fits to the limited installation sapce. Combining advanced signal processing technology with multiple types of electrical output, EV40P are capable of matching various upper control computers.

### Features

- Rerverse connection protection; short circuit protection

#### Mechanical Characteristics

Shaft diameter (mm)	Ф6H7/Ф8H7
Protection grade	IP66 standard, IP67 optional
Max. speed/minute	6000
Max. load capacity of the shaft	60N axial
	100N radial
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000HZ
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	1.9×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.08Nm
Body material	Al-alloy
Housing material	Zn-alloy
Operating temperature	-20~+85°C
Storage temperature	-25~+100°C
Weight	110g

Regular resolution: 10, 20, 30, 40, 50, 60, 70, 80, 90, 100, 200, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1250, 2000, 2500, 4000, 5000

Note: Bold part is normally in stock. Other resolution are available only upon request.

#### **Electrical Characteristics**

Output circuit	RS422	Push-pull	
Resolution	Max.5000ppr	Max.5000ppr	
Supply voltage(VDC)	5±0.25 or 10-30	10-30	
Power consumption(no load)	≤80mA	≤125mA	
Permissible load(channel)	±50mA	±80mA	
Pulse frequency	Max.800kHz	Max. 800kHz	
Signal level high	Min. 3.4V	Min.Ub-1.8	
Signal level low	Max. 0.4V	Max. 2.0V	
Rise time Tr	Max. 200ns	Max.1µs	
Fall time Tf	Max. 200ns	Max.1µs	



- Stainless steel shaft ensures safety and stability in operation
- Optional types of flange connection offers more flexibility
- Metal casting housing for greater shock resistance
- Side cabling design greatly saves the installation space and simplifies wiring

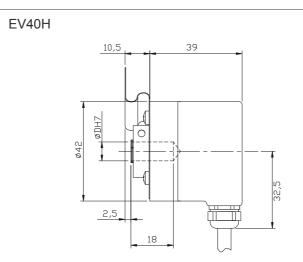
## Topydic Small Hollow Shaft Incremental Encoder EV40P

## Terminal Configuration

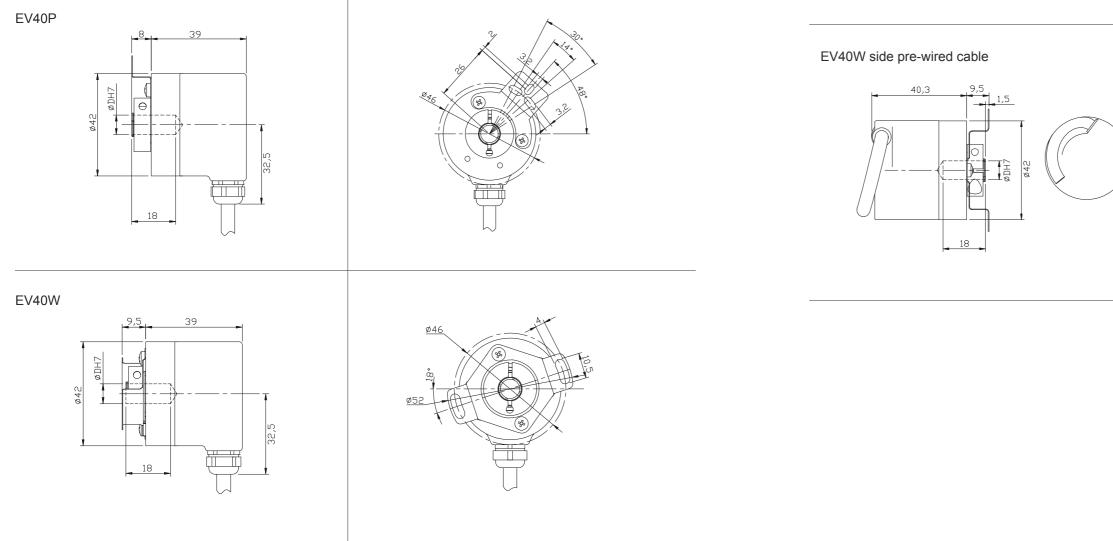
Signal	0V	+U <sub>b</sub>	А	Ā	В	B	Z	Z	0V Sen	+U <sub>b</sub> Sen	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	GY/PK	RD/BU	÷
Pin	10	12	5	6	8	1	3	4	11	2	PH

## Topydic Small Hollow Shaft Incremental Encoder EV40P

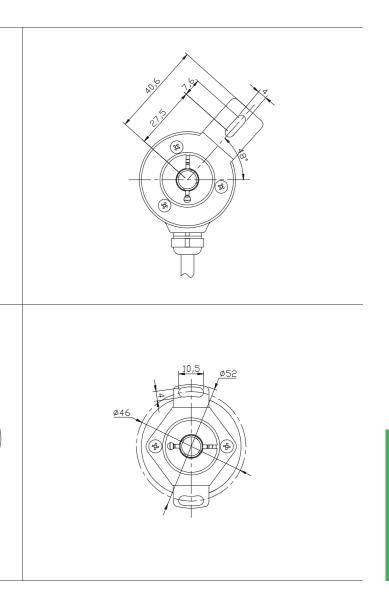
## Dimensions



## Dimensions

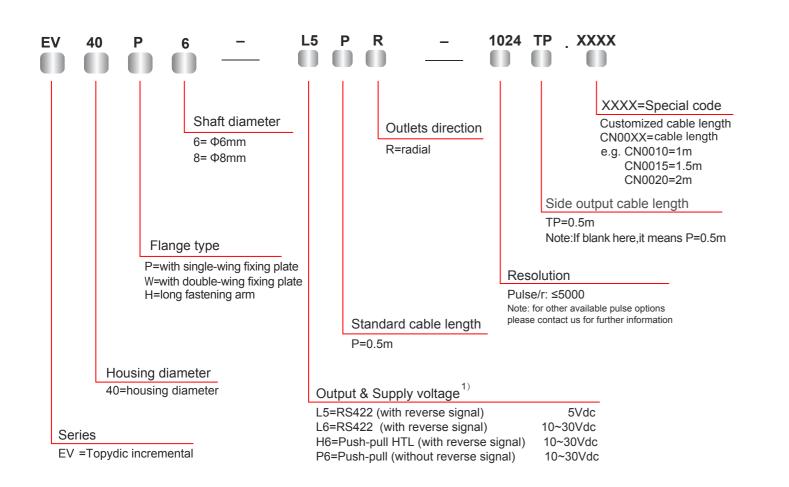






## Topydic Small Hollow Shaft Incremental Encoder EV40P

Order Code:



<sup>1)</sup> When the voltage supply within the limited range and only one signal channel is connected improperly at certain moment: if UB=5V, it's pXremitted to connect to signal channals, 0V or UB; if UB>5V, it's premitted to connect to signal channals or 0V.

## Topydic Series Shaft Incremental EV50A



### Mechanical Characteristics

Shaft diameter $\Phi 6/\Phi 8/\Phi 10/\Phi 12/\Phi 1/4"/\Phi 3/8"$ Protection GradeIP65 (without oil seal)IP67 (with oil seal)IP67 (with oil seal)Speed12000 rpm (without oil seal)Max. load capacity of the shaft40N axialShock resistance50G/11msVibration resistance10G 10~2000HZBearing life109 revolutionMoment of inertia $1.9\chi 10^{-6}$ kgm²Starting torque<0.01Nm (IP65)
$\begin{tabular}{ c c c c c } \hline IP67 & (with oil seal) & & & & & & & & & & & & & & & & & & &$
Speed       12000 rpm (without oil seal)         6000 rpm (with oil seal)         Max. load capacity of the shaft       40N axial         80N radial         Shock resistance       50G/11ms         Vibration resistance       10G 10~2000HZ         Bearing life       10 <sup>9</sup> revolution         Moment of inertia       1.9χ10 <sup>-6</sup> kgm²
$\begin{array}{c} 6000 \ \mathrm{rpm} \ (\mathrm{with} \ \mathrm{oil} \ \mathrm{seal}) \\ \\ \mathrm{Max.} \ \mathrm{load} \ \mathrm{capacity} \ \mathrm{of} \ \mathrm{the} \ \mathrm{shaft} \ & 40\mathrm{N} \ \mathrm{axial} \\ \\ & 80\mathrm{N} \ \mathrm{radial} \\ \\ \mathrm{Shock} \ \mathrm{resistance} \ & 50\mathrm{G}/11\mathrm{ms} \\ \\ \mathrm{Vibration} \ \mathrm{resistance} \ & 10\mathrm{G} \ 10\sim2000\mathrm{HZ} \\ \\ \mathrm{Bearing} \ \mathrm{life} \ & 10^9 \ \mathrm{revolution} \\ \\ \mathrm{Moment} \ \mathrm{of} \ \mathrm{inertia} \ & 1.9\chi10^{-6} \ \mathrm{kgm^2} \\ \end{array}$
Max. load capacity of the shaft     40N axial       80N radial       Shock resistance     50G/11ms       Vibration resistance     10G 10~2000HZ       Bearing life     10 <sup>9</sup> revolution       Moment of inertia     1.9 <sub>X</sub> 10 <sup>-6</sup> kgm <sup>2</sup>
80N radial       Shock resistance       50G/11ms       Vibration resistance       10G 10~2000HZ       Bearing life       10 <sup>9</sup> revolution       Moment of inertia       1.9 <sub>X</sub> 10 <sup>-6</sup> kgm <sup>2</sup>
Shock resistance       50G/11ms         Vibration resistance       10G 10~2000HZ         Bearing life       10 <sup>9</sup> revolution         Moment of inertia       1.9χ10 <sup>-6</sup> kgm <sup>2</sup>
Vibration resistance       10G 10~2000HZ         Bearing life       10 <sup>9</sup> revolution         Moment of inertia       1.9 <sub>X</sub> 10 <sup>-6</sup> kgm <sup>2</sup>
Bearing life     10 <sup>9</sup> revolution       Moment of inertia     1.9χ10 <sup>-6</sup> kgm <sup>2</sup>
Moment of inertia 1.9χ10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque
<0.05Nm (IP67)
Body material Al-alloy
Housing material Al-alloy
Operating temperature -40~+85°C
Storage temperature -45~+90°C
approx. 400g
Weight

Resolution: 100, 200, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1250, 2000, 2048, 2500, 3600, 4096, 5000 Attention: the products with above resolutions are standing inventory; others on request.

#### **Electrical Characteristics**

Output circuit	RS422	Push-pull
Supply voltage (VDC)	5±0.25 or 10~30	10~30
Power consumption (no load)	typ. 40mA	typ. 50mA
	max. 90mA	max. 100mA
Permissible load (channel)	max. ±20mA	max. ±30mA
Pulse frequency	max. 300kHz	max. 300kHz
Signal level high	min. 2.5V	min. Ub-1V
Signal level low	max. 0.5V	max. 0.5V
Rise time Tr	max. 200ns	max. 1µs
Fall time Tf	max. 200ns	max. 1µs

#### **Terminal Configuration**

Signal	0V	+Ub	А	Ā	В	Ē	Z	Ī	0V Sen	+Ub Sen	Shield	
Color Code	WH	BN	GN	YE	GY	PK	BU	RD	GY/PK	RD/BU	÷	
Pin (12-pin)	10	12	5	6	8	1	3	4	11	2	PH	
Pin (5-pin)	1	2	3	-	4	-	5	-			PH	
Pin (8-pin)	1	2	3	4	5	6	7	8			PH	

#### Descriptions

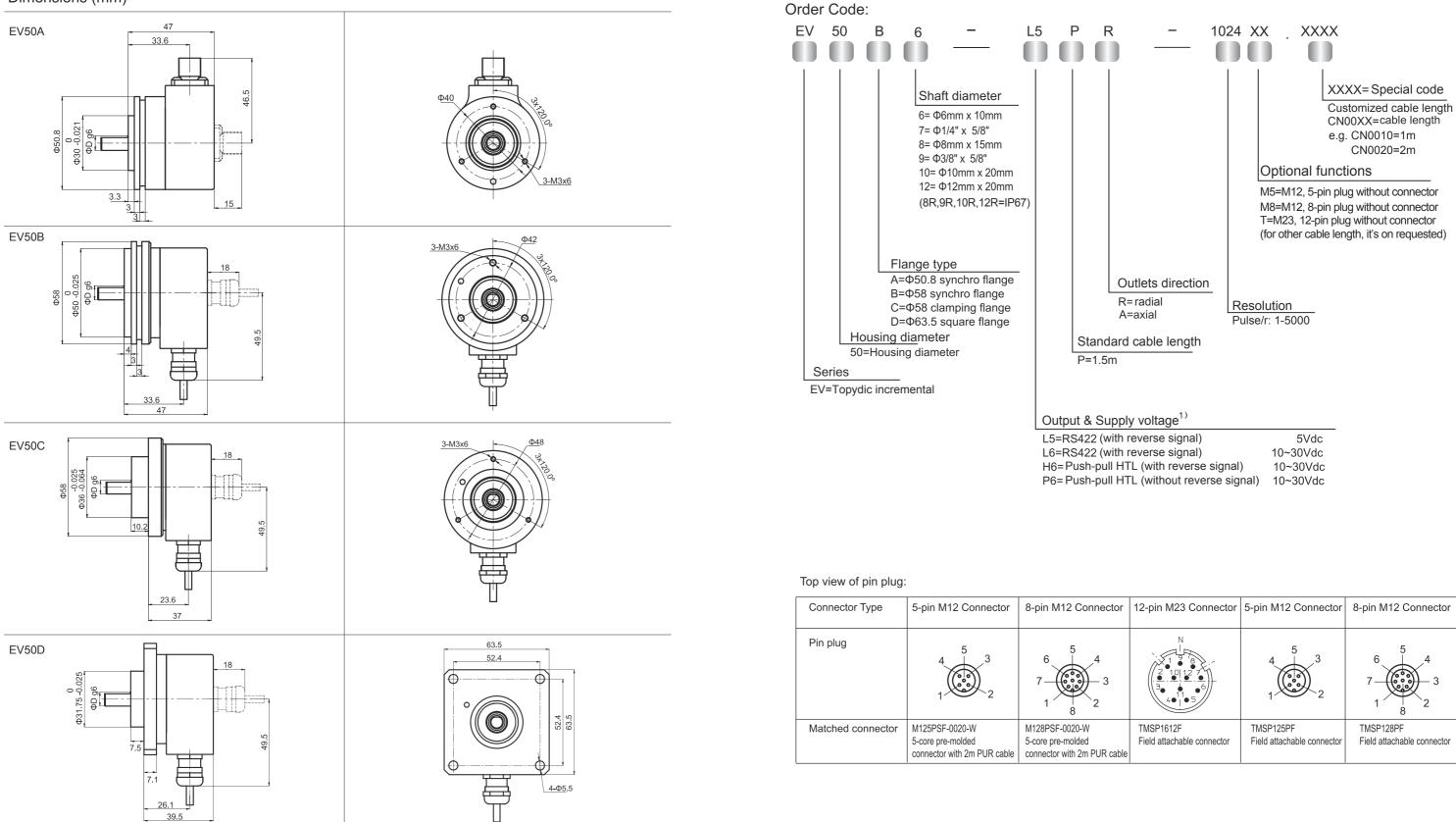
Topydic series shaft incremental encoder EV50A, with double-bearing and casting housing, owns excllent performance to resist mechanical shocks and can be used in various industrial environments; being compatible with standard flange types-50mm and 58mm, it can meet different application requirements;its wide voltage range, reverse connection and short circuit protection can effectively prevent the impact to the encoder due to mis-wiring.

#### Features

- Resolution up to 5000ppr; pulse frequency up to 300kHz
- Hollow shaft diameter, Φ6~Φ12mm
- Be compatible with standard flange types-50mm and 58mm
- Φ50mm metal casting housing for limited installation space
- Operating temperature, -40~+85°C; IP67 protection grade for outdoors application
- Multi signal output interfaces to meet different types of data aquisition of upper computer
- Optional output types-with cable, M12 connector and M23 connector
- Reverse connection and short circuit protection to ensure the safety <sup>1)</sup>

## Topydic Series Shaft Incremental EV50A

#### Dimensions (mm)





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2	n lu z	vol	ltage <sup>1</sup>	,
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Topydic Series Shaft Incremental EV50A

ith reverse signal)	5Vdc
ith reverse signal)	10~30Vdc
HTL (with reverse signal)	10~30Vdc
HTL (without reverse signal)	10~30Vdc

tor	12-pin M23 Connector	5-pin M12 Connector	8-pin M12 Connector
	N 19/60 2 10/12 7 3 410 5	4 5 3 1 2 2	
cable	TMSP1612F Field attachable connector	TMSP125PF Field attachable connector	TMSP128PF Field attachable connector

## Topydic Series Shaft Incremental EV50P



#### Descriptions

Topydic series shaft incremental encoder EV50P, with double-bearing and casting housing, owns excllent performance to resist mechanical shocks and can be used in various industrial environments; stainless steel through-hole, diameter of which up to 15mm; its wide voltage range, reverse connection and short circuit protection can effectively prevent the impact to the encoder due to mis-wiring.

#### Features

- Resolution up to 5000ppr; pulse frequency up to 300kHz
- Wide range of shaft diameter, Φ6~Φ15mm
- Hollow shaft installation, robust metal casting housing
- Operating temperature, -40~+85°C; IP67 protection grade for outdoors application
- Housing thickness up to 46.3mm for limited installation space
- Multi signal output interfaces to meet different types of data aquisition of upper computer
- Optional output types-with cable, M12 connector and M23 connector
- Reverse connection and short circuit protection to ensure the safety

#### Mechanical Characteristics

Shaft diameter (mm)	Φ6/Φ8/Φ10/Φ12/Φ14/Φ15/Φ1/4"/Φ3/8"/Φ1/2"/Φ5/8"
Protection grade	IP65 (without oil seal)
	IP67 (with oil seal)
Speed	12000 (without oil seal)
	6000 (with oil seal)
Max. load capacity of the shaft	40N axial
	80N radial
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000HZ
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	6x10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.03Nm (IP65)
	<0.08Nm (IP67)
Body material	Al-alloy
Housing material	Al-alloy
Operating temperature	-40∼+85°C
Storage temperature	-45∼+90°C
Weight	Approx. 400g

Regular resolution: 100, 200, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1250, 2000, 2048, 2500, 3600, 4096, 5000

Note: other resolutions on request

### **Electrical Characteristics**

Output circuit	RS422	Push-pull
Supply voltage(VDC)	5±0.25 or 10~30	10~30
Power consumption(no load)	typ. 40mA	typ. 50mA
	max. 90mA	max. 100mA
Permissible load(channel)	max. ±20mA	max. ±30mA
Pulse frequency	max. 300kHz	max. 300kHz
Signal level high	min. 2.5V	min. Ub-1V
Signal level low	max. 0.5V	max. 0.5V
Rise time Tr	max. 200ns	max. 1µs
Fall time Tf	max. 200ns	max. 1µs

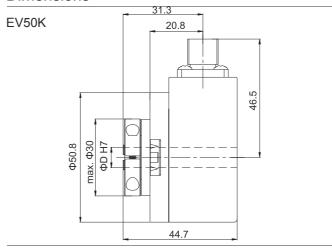
1) When the voltage supply within the limited range and only one signal channel is connected improperly at certain moment: if UB=5V, it's premitted to connect to signal channals, 0V or UB; if UB>5V, it's premitted to connect to signal channals or 0V.

## Topydic Series Shaft Incremental EV50P

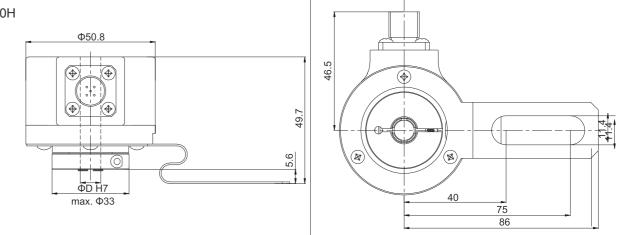
#### Terminal Configuration

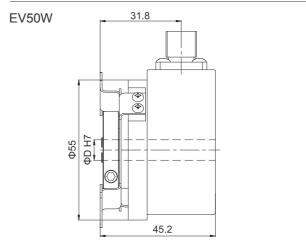
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Signal	0V	+Ub	А	Ā	В	Ē	Z	Ī	0V Sen	+U <sub>b</sub> Sen	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	GY/PK	RD/BU	÷
Pin(12-pin)	10	12	5	6	8	1	3	4	11	2	PH
Pin(5-pin)	1	2	3	-	4	-	5	-			PH
Pin(8-pin)	1	2	3	4	5	6	7	8			PH

#### Dimensions

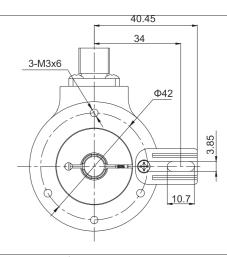


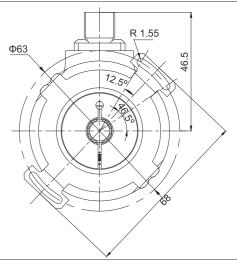
EV50H

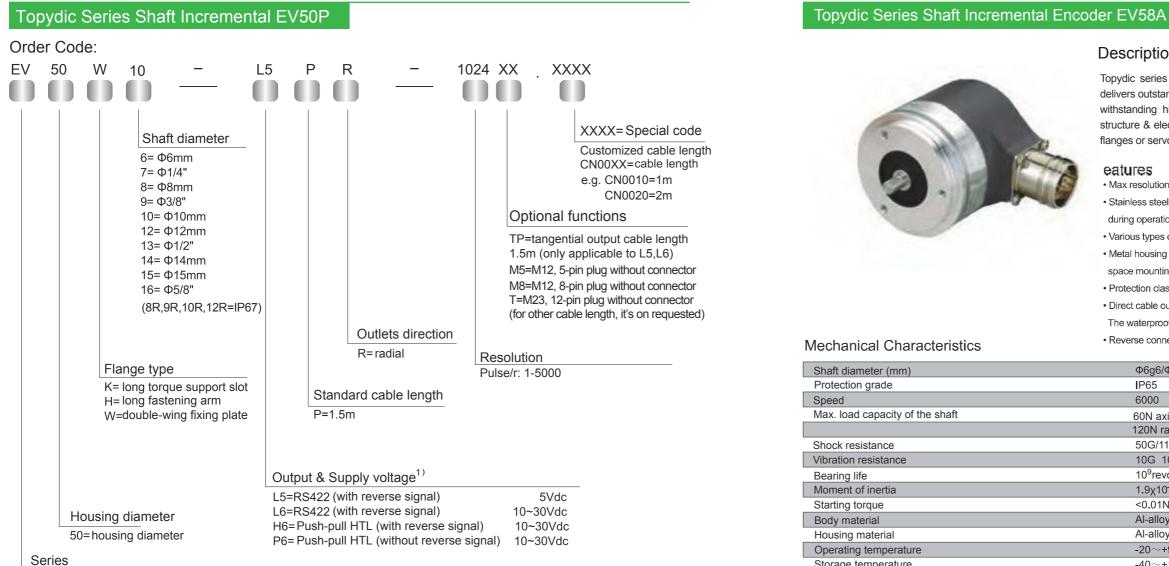












EV=Topydic incremental

#### Top view of pin plug:

Connector type	5-pin M12 connector	8-pin M12 connector	12-pin M23 connector	5-pin M12 connector	8-pin M12 connector
Pin plug	4 5 3 1 2 2		$\begin{array}{c} N\\ 1\\ 9\\ 2\\ 1\\ 9\\ 2\\ 1\\ 9\\ 4\\ 1\\ 9\\ 4\\ 1\\ 1\\ 9\\ 4\\ 1\\ 1\\ 9\\ 4\\ 1\\ 1\\ 9\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\ 1\\$		
Matched connector	M125PSF-0020-W 5-core pre-molded connector with 2m PUR cable	M128PSF-0020-W 8-core pre-molded connector with 2m PUR cable	TMSP1612F Field attachable connector	TMSP125PF Field attachable connector	TMSP128PF Field attachable connector

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Shaft diameter (mm)	Ф6д6/Ф8д6/Ф10д6	
Protection grade	IP65	
Speed	6000	
Max. load capacity of the shaft	60N axial	
	120N radial	
Shock resistance	50G/11ms	
Vibration resistance	10G 10~2000HZ	
Bearing life	10 <sup>9</sup> revolution	
Moment of inertia	<b>1.9χ10<sup>-6</sup>kg</b> m <sup>2</sup>	
Starting torque	<0.01Nm IP65	
Body material	Al-alloy	
Housing material	Al-alloy	
Operating temperature	-20∼+90°C	
Storage temperature	-40~+100°C	
Weight	300g	

Regular resolution: 360, 400, 500, 512, 600, 800, 1000, 1024, 2000, 2500, 4000, 2048, 4096, 5000 Note: other resolutions on request

#### **Electrical Characteristics**

Output circuit	RS422
Resolution	Max.5000ppr
Supply voltage(VDC)	5±0.25 or 10-30
Power consumption(no load)	≤80mA
Permissible load(channel)	±50mA
Pulse frequency	Max.300kHz
Signal level high	Min.3.4V
Signal level low	Max.0.4V
Rise time Tr	Max 200ns
Fall time Tf	Max 200ns



### Descriptions

Topydic series encoders EV58A are widely used in industrial environments. It delivers outstanding performance in mechanical shock resistance and is capable of withstanding higher axial and radial loads. Its flexible and variant mechanical structure & electrical circuit designs ensure perfect matches with multiply types of flanges or servo motors. They are compatible with all control computers.

- Max resolution is up to 5000pulse/r, output frequency is up to 300 kHz
- Stainless steel shaft  $\Phi 6/\Phi 8/\Phi 10$ , flexible coupling connection ensures encoder safety during operation
- Various types of flanges, including imperial sizes
- Metal housing for greater shock resistance; compact structure is suited for confined space mounting
- Protection class IP65
- Direct cable output or connector is more flexible and easy for maintenance
- The waterproof rubber ends ensure safety during operation
- Reverse connection protection Short circuit protection

Push-pull	
Max.5000ppr	
10-30	
≤125mA	
±80mA	
Max.300kHz	
Min. Ub-1.8	

Max.2.0V Max 1µS Max 1µS

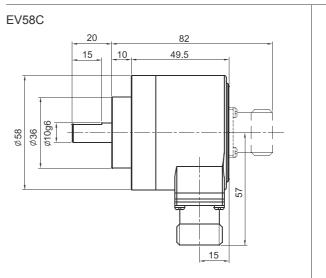
## Topydic Series Shaft Incremental Encoder EV58A

## Terminal Configuration

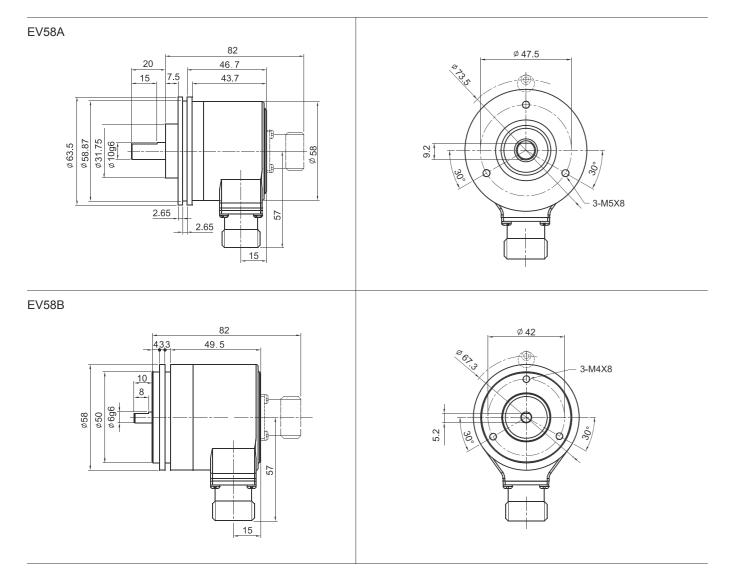
Signal	0V	+Ub	А	Ā	В	B	Z	Ī	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	÷
Pin	10	12	5	6	8	1	3	4	PH

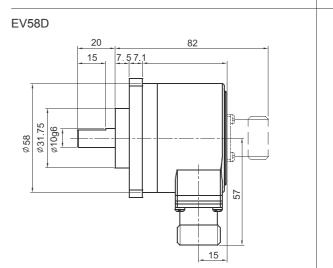
## Topydic Series Shaft Incremental Encoder EV58A

## Dimensions

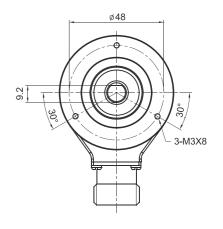


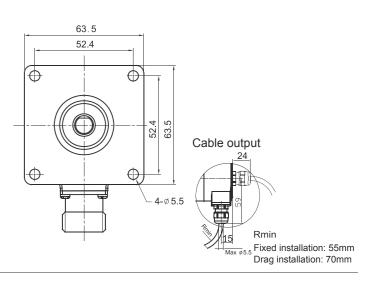
## Dimensions





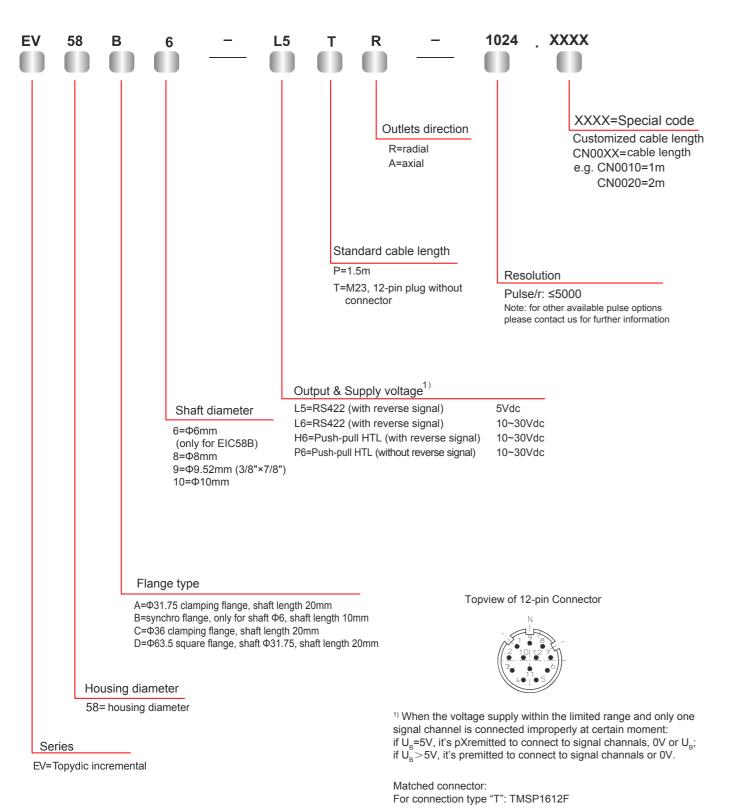






#### Topydic Series Shaft Incremental Encoder EV58A

#### Order Code:



## Topydic Series Hollow Shaft Incremental Encoder EV 58P

#### Features

- Resolution up to 5000ppr; pulse frequency up to 300kHz
- Wide range of shaft diameter, Φ8...Φ15mm

- Multi signal output interfaces to meet diferent types of data aquisition of upper computer

### **Mechanical Characteristics**

	Shaft diameter (mm)	Φ8
	Protection Grade	IP
	Speed	60
	Max. load capacity of the shaft	40
		80
	Shock resistance	50
	Vibration resistance	10
	Bearing life	10
ſ	Moment of inertia	ар
	Starting torque	<0
ſ	Body material	Al
	Housing material	Aŀ
	Operating temperature	-20
	Storage temperature	-4(
ſ	Weight	ар

Regular resolution: 256, 300, 360, 400, 500, 512, 600, 800, 1000, 1024, 1200, 1250, 2000, 2048, 2500, 3600, 4096, 5000 Note: other resolutions on request

#### **Electrical Characteristics**

Output circuit	RS422	Push-pull
Supply voltage (VDC)	5±0.25 or 1030VDC	1030VDC
Power consumption (no load)	typ. 40mA	typ. 50mA
	max. 90mA	max. 100mA
Permissible load	max. ±20mA	max. ±30mA
Pulse frequency	max. 300kHz	max. 300kHz
Signal level high	min. 2.5VDC	min. Ub-1VDC
Signal level low	max. 0.5VDC	max. 0.5VDC
Rise time Tr	max. 200ns	max. 1µs
Fall time Tf	max. 200ns	max. 1µs

<sup>1)</sup> When the voltage supply within the limited range and only one signal channel is connected improperly at certain moment:

if  $U_B$ =5VDCs premitted to connect to signal channals, 0VDC or  $U_B$ ;

if  $U_{\rm B}$  >5VDC , its premitted to connect to signal channels or 0VDC.



#### Descriptions

Topydic series encoders EV58P, with double-bearing design, are widely used in industrial environments. It delivers outstanding preformance in mechanical shock resistance. It adopts stainless steel hollow shaft design with max. shaft diameter of  $\Phi$ 15mm and is able to withstand higher axial and radial loads. requirements. Its wide voltage range, reverse connection and short circuit protection can effectively

- Operating temperature, -20...+80°C; IP65
- Thickness of 34.5mm, applicable for installation with limited space
- Reverse connection and short circuit protection to ensure the safety <sup>1</sup>)

Þ8/Φ10/Φ12 /Φ14/Φ15
P65
6000rpm
ON axial
30N radial
50G/11ms
0G 102000HZ
0 <sup>9</sup> revolution
approx. 6x10 <sup>-6</sup> kgm <sup>2</sup>
:0.03Nm
Al-alloy
Al-alloy
20 +80°C
40 +95°C
approx. 400g

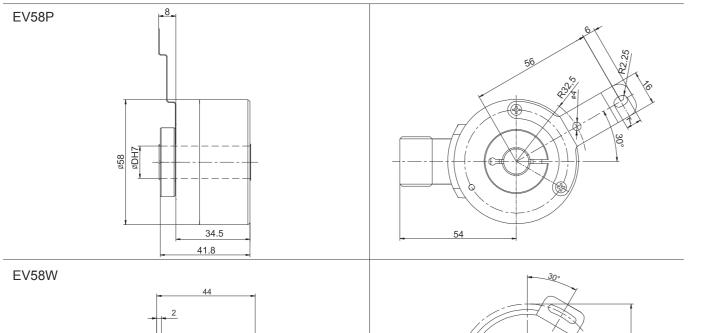
## Topydic Series Hollow Shaft Incremental Encoder EV 58P

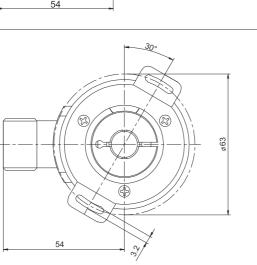
### **Terminal Assignment**

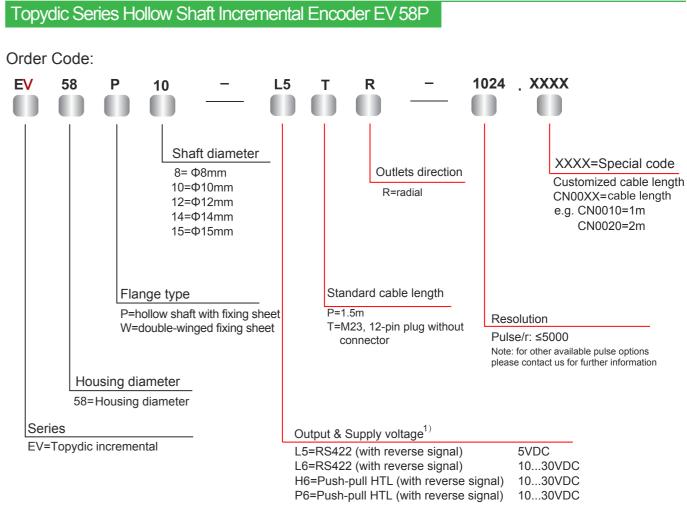
Signal	0V	+Ub	А	Ā	В	Ē	Z	Ī	0V Sen	+U <sub>b</sub> Sen	Shield
Color Code	WH	BN	GN	YE	GY	PK	BU	RD	GY/PK	RD/BU	÷
12-pin	10	12	5	6	8	1	3	4	11	2	PH

### Dimensions (mm):

Š,







T type connection: 12-pin M23 Connector

TMSP1612F

Field attachable connector

<sup>1)</sup>When provided power voltage is correct: Short-circuit to channel, 0V, or +UB is permitted when UB=5VDC; Short-circuit to channel or 0V is permitted when UB=10...30VDC





22 (with reverse signal)	5VDC
22 (with reverse signal)	1030VDC
h-pull HTL (with reverse signal)	1030VDC
n-pull HTL (with reverse signal)	1030VDC

### Heavydic Large Hollow Shaft Incremental Encoder EV90P



#### Descriptions

Heavydic large hollow shaft incremental encoder EV90P are specially designed for heavy industries and heavy-loaded shaft applications. It delivers perfect performance of mechanical shock resistance, and is capable of withstanding higher axial and radial loads. It can be directly installed onto the drive shaft with crutch arm or fixing sheet for flexible connection. Its resolution is up to 2500ppr, which ensures accurate control and application safety.

#### Features

Robust metal housing against greater shock;	Stainless steel hollow shaft with diameter of
compact structure for limited installation space	$\Phi 25/\Phi 30/\Phi 38/\Phi 45;$ installed by "C" lock ring

- Resolution up to 2500ppr; protection grade of IP65
- for easy maintemance; water-proof design Compact hollow shaft design to save both space and cost
- to ensure safety Crutch arm and fixing sheet provide greater flexibility Reverse connection / short circuit protection
- Mechanical Characteristics

Hollow shaft diameter (mm)	Ф25/Ф30/Ф38/Ф45H7
Protection Grade	IP <sub>65</sub>
Speed	3500 rpm
Max. load capacity of the shaft	80N axial
	140N radial
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000HZ
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	approx.15×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.1Nm with oil seal
Body material	Al-alloy
Housing material	Al-alloy
Operating temperature	-20∼+80°C (-40∼+80°C optional)
Storage temperature	-45∼+85°C
Weight	approx. 900g

Regular resolution: 1024, 2048

Note: other resolutions on request

#### **Electrical Characteristics**

Output circuit	RS422	Push-pull
Resolution	Max 2500ppr	Max 2500ppr
Supply voltage (VDC)	5±0.25 or 10-30	10-30
Power consumption (no load)	≤80mA	≤125mA
Permissible load	±20mA	±40mA
Pulse frequency	Max 300kHz	Max 300kHz
Signal level high	Min 3.4V	Min Ub-1.8
Signal level low	Max 0.4V	Max 2.0V
Rise time Tr	Max 200ns	Max 1µS
Fall time Tf	Max 200ns	Max 1µS

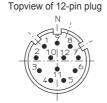
#### **Terminal Configuration**

Signal	0V	+Ub	А	Ā	В	Ē	Z	Ī	0V Sen	+U <sub>b</sub> Sen	Shield
Color Code	WH	BN	GN	YE	GY	PK1	BU	RD	GY/PK	RD/BU	÷
Pin	10	12	5	6	8	1	3	4	11	2	PH

1) When the voltage supply within the limited range and only one signal channel is connected improperly at certain moment: if  $U_{\rm p}$ =5V, it's premitted to connect to signal channals, 0V or  $U_{\rm B}$  ; if  $U_{\rm B}$  >5V, it's premitted to connect to signal

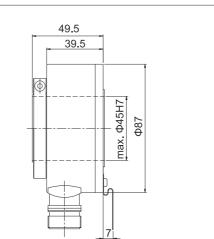
channals or 0V.

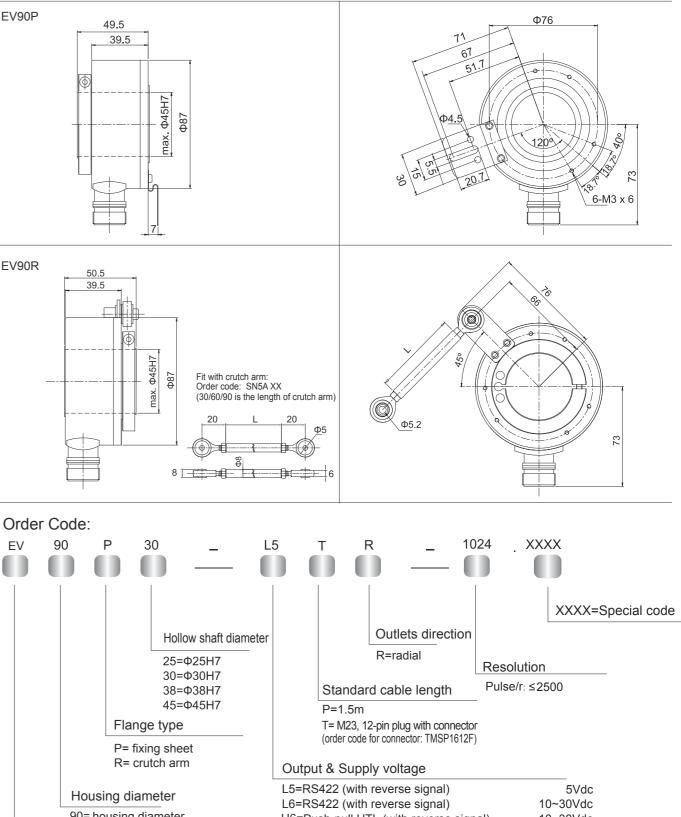
Matched connector: the compatible connector with type of connection "T" is TMS1612F.

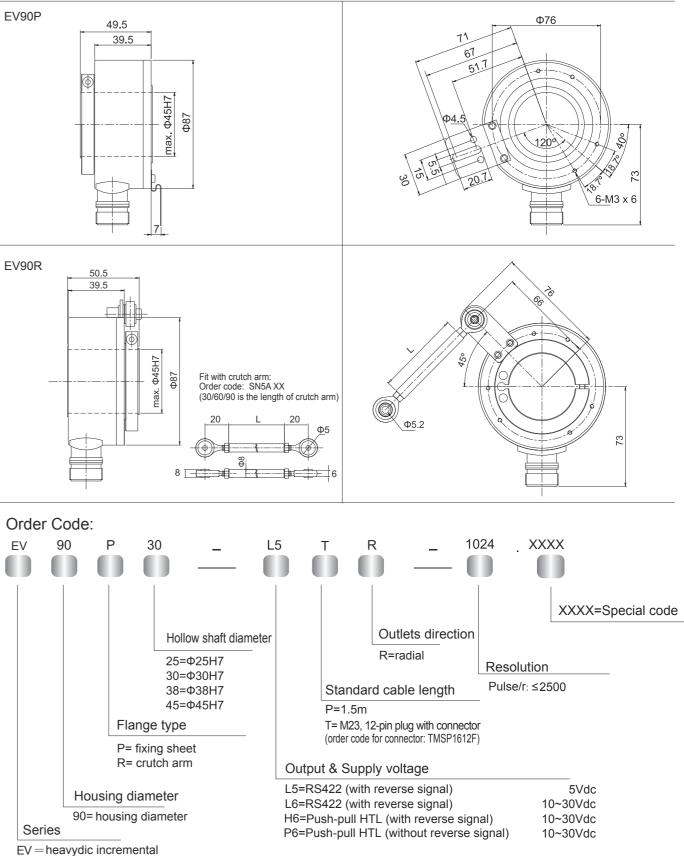


## Heavydic Large Hollow Shaft Incremental Ercoder EV90P

Dimensions (mm)









## Topydic Series Large Hollow Shaft Incremental Encoder EV150P



#### Description

Topydic series large hollow shaft encoders EV150P are widely used in industrial environments in which direct installation on the drive shaft for speed feedback is required. It delivers excellent performance in withstanding mechanical shock and higher axial and radial loads. Hollow shaft structure could be directly installed onto the drive shaft, and crutch arm or block-pin accessories provide greater flexibility to prolong the usability of the encoder. EV150P delivers resolution up to 2048ppr, and guaranteen both precise measurement control and safety in loading. It is the most recommended product for its high quality and affordability.

#### Features

- Crutch are or block-pin accessories provide the greatest flexibility
- Resolution 2048ppr, IP64 guarantees precision and safety
- Compact hollow shaft design is both a space and cost-saver
- Metal housing for greater shock resistance, compact structure is suited for confined mounting space
- Stainless steel hollow shaft  $\Phi$ 60H7  $\Phi$ 80H7 , "C"lock ring

Reverse connection protection.Short circuit protection

- · Cable output or connector is flexible and easy for maintenance
- The waterproof rubber ends ensures safety

### Mechanical Characteristics

Hollow shaft diameter(mm)	Ф60Н7 — Ф80Н7
Protection acc. to EN 60529	IP64
Speed	3000RPM
Max load capacity of the shaft	100N axial
	200N radial
Shock resistance	50G/11ms
Vibration resistance	10 G 10~2000Hz
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	<15 x 10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.25Nm max.
Body material	AL-alloy
Housing material	AL-alloy + green paint
Operating temperature	-20~+90°C
Storage temperature	-40~+100°C
Weight	1800g

Resolution: 1000, 1024, 2048 Attention: Bold part is in stock, others on request

#### **Electrical Characteristics**

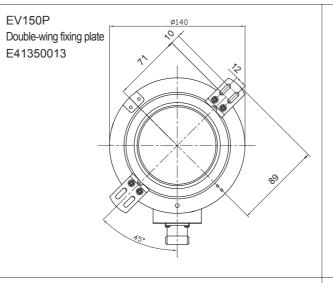
Output circuit	RS422	Push-pull
Resolution	Max.2048ppr	Max.2048ppr
Supply voltage(VDC)	5±0.25 or 10-30	10-30
Power consumption (no load)	≤80mA	≤125mA
Permissible load (channel)	±50mA	±80mA
Pulse frequency	Max.800kHz	Max.800kHz
Signal level high	Min.3.4V	Min.Ub-1.8
Signal level low	Max.0.4V	Max.2.0V
Rise timeTr	Max 200ns	Max 1µs
Fall timeTf	Max 200ns	Max 1µs

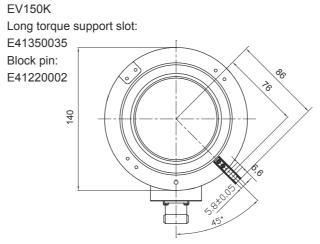
#### **Terminal Assignment**

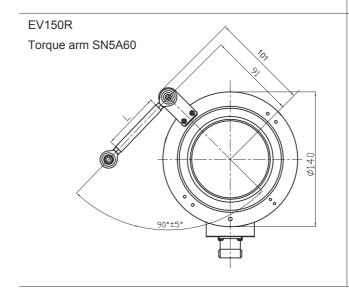
Signal	0V	+Ub	А	Ā	В	B	Z	Z	0V Sen	+Ub Sen	Shield
Color	WH	BN	GN	YE	GY	PK	BU	RD	GY/ PK	RD/ BU	÷
Pin	10	12	5	6	8	1	3	4	11	2	PH

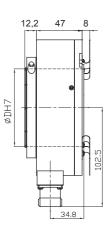
## Topydic Series Large Hollow Shaft Incremental Encoder EV150P

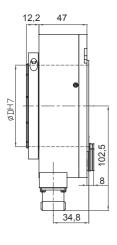
#### Dimensions







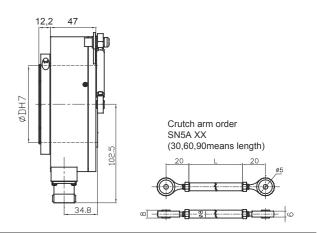






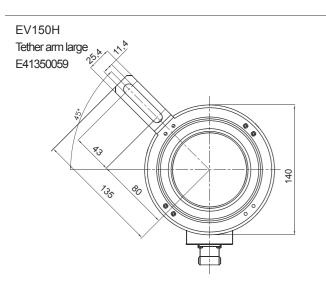


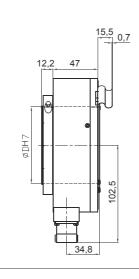
Rmin Fix installation: 55mm Draw installation: 70mm



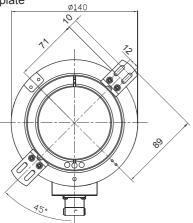
## Topydic Series Large Hollow Shaft Incremental Encoder EV150P

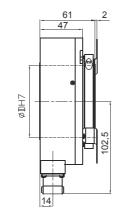
## Dimensions



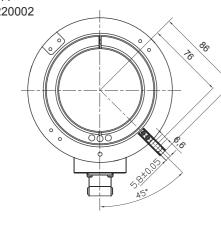


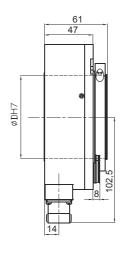
EV150RP Double-wing fixing plate E41350013





EV150RK Long torque support slot:E41350035 Block pin:E41220002





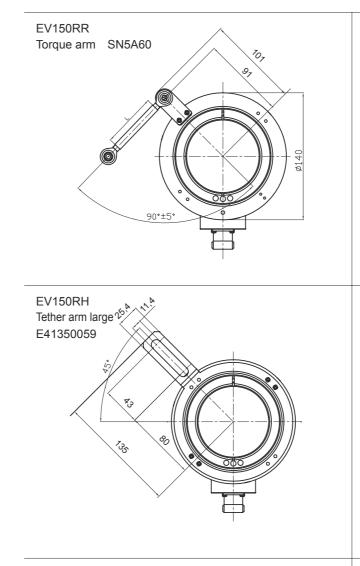
Cable output



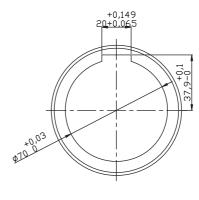
Rmin Fix installation: 55mm Draw installation: 70mm

## Topydic Series Large Hollow Shaft Incremental Encoder EV150P

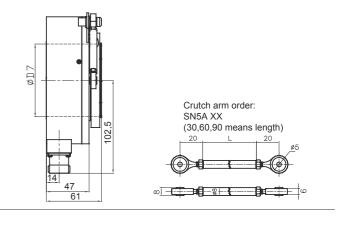
#### Dimensions

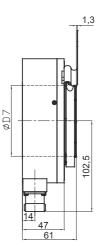


Keyway shaft



EV150P Keyway





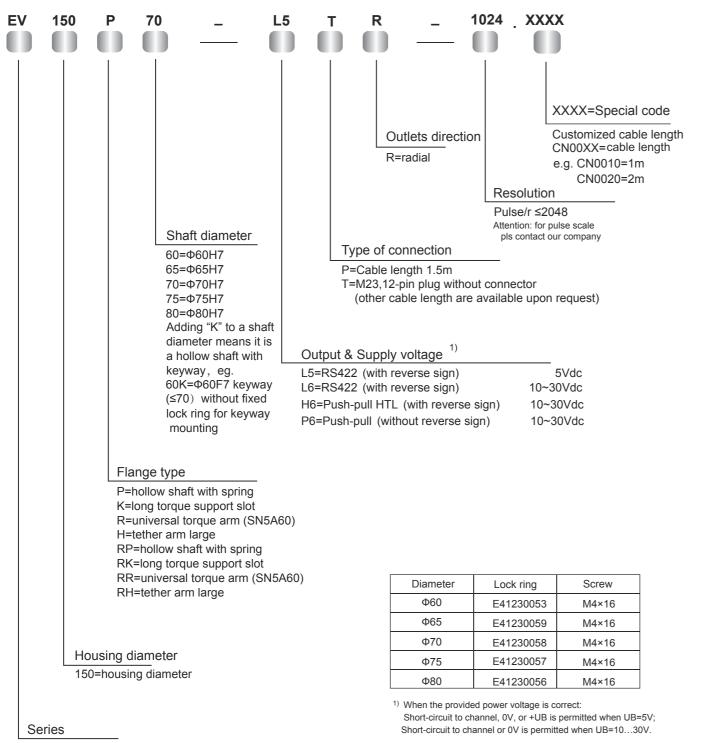
Cable output



Rmin Fix installation: 55mm Draw installation: 70mm

## Topydic Series Large Hollow Shaft Incremental Encoder EV150P

Order Code:



Connector order:

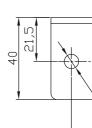
matching "T" connector: TMSP1612F

## **EVL Support**

### EVL support:

Type: EVL-L38A Material: carbon steel Surface treatment: zinc plating Applicable for: shaft encoder 38 series Installation: with flange





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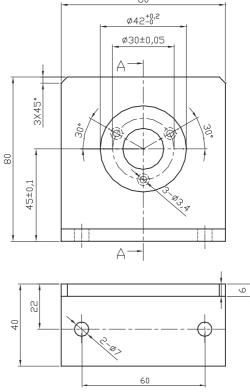
45±0.1

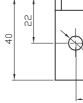
### **EVL** support:

Applicable for shaft encoder 40 with clamping flange

Material: Al

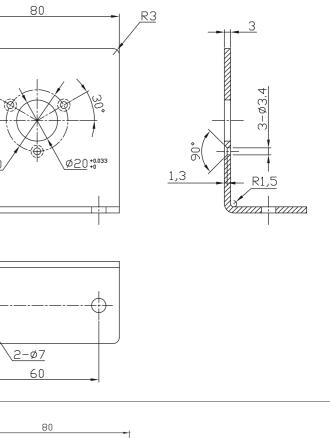
Type: EVL-L40A

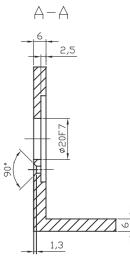




EV = Topydic incremental







## **EVL Support**

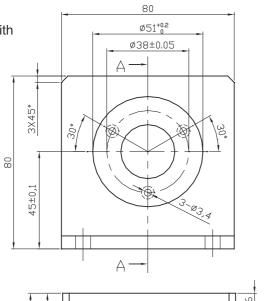
## EVL support:

Applicable for shaft encoder 50A with clamping flange

Material: Al

Type: EVL -L50A



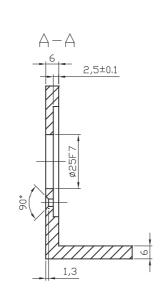


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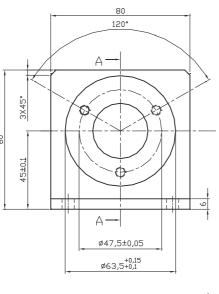


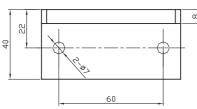
## EVL support:

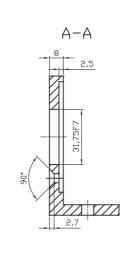
Applicable for shaft encoder 58A with clamping flange

Material: Al

Type: EVL-L58A







## **EVL Support**

## EVL support:

Applicable for shaft encoder 58 with clamping flange

Material: Al

Type: EVL*-*L58C

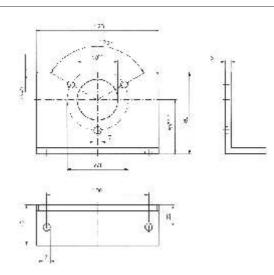




## EVL support:

Applicable for shaft encoder 90 with clamping flange Material: Al

Type: EVL**-**L90A

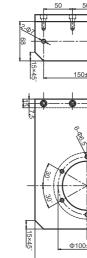


## EVL support:

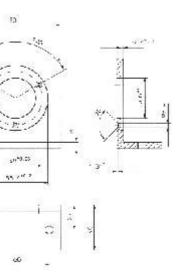
Applicable for shaft encoder 115 with clamping flange Material: Al

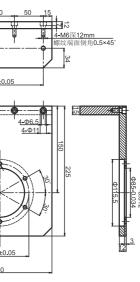
Туре:

EVL-L115A









## Coupling



#### Description

Flexible precision couplings are essential parts for the transmission of rotational motion to the encoder shaft. Couplings are designed in AL-alloy and are composed by a cylindrical body on which there is a helicoidal groove. With the perfect balancing of the rotating body, the couplings do not have critical points subject to breakage and are completely frictionless. Moreover, they perfectly transmit the rotation motion, even in the case of axial misadjustment and misalignment. The couplings do not require any maintenance. The internal drain allows the coupling to have the minimum distance of 6.12mm between the shafts.

#### Features

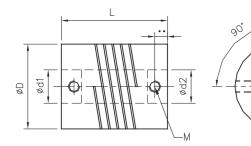
- Torsional rigidity
- Ability to support slight shaft misadjustments
- Ability to absorb small axial shift of the shaft

Note: Metric and Imperial sizes: A1=6.35mm A2=9.525mm A3=12.7mm

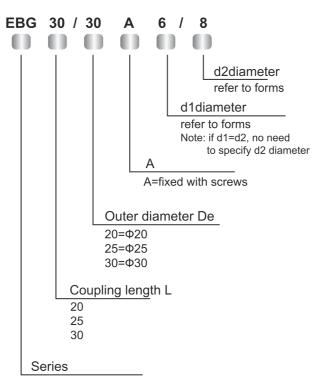
#### Screw flexible coupling:

Code	Φd1/Φd2Shaft diameter	ΦD	L	L1	Twisting moment M	lax. angular displacement	Max. speed	Screw(M)	Material
EBG20/20A	3 4 5 6 6.35(A1)	20	20	2.55	0.8N.m	1°	8000r/min	M3	AL-alloy
EBG25/25A	5 6 6.35(A1) 8 9.525(A2) 10	25	25	3.55	1.8N.m	1°	8000r/min	M4	AL-alloy
EBG30/30A	6 8 9.525(A2) 10 12 12.7(A3)	30	30	4.15	2.7N.m	1°	8000r/min	M5	AL-alloy
EBG38/38A0000	8 9.525(A2) 10 12 12.7(A3) 14 15	38	38	4.15	6.3N.m	1°	8000r/min	M5	AL-alloy
EBG50/50A0000	12 12.7(A3) 14 15 16 18 19	50	50	5.25	19.5N.m	1°	8000r/min	M6	AL-alloy

### **Coupling Dimensions:**



### Order Code



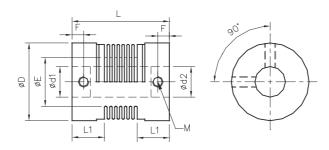
#### EBG=Screw-type flexible coupling

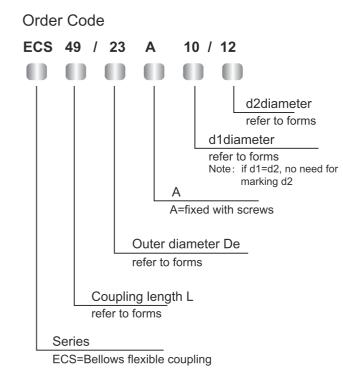
## Coupling

#### Bellow flexible coupling

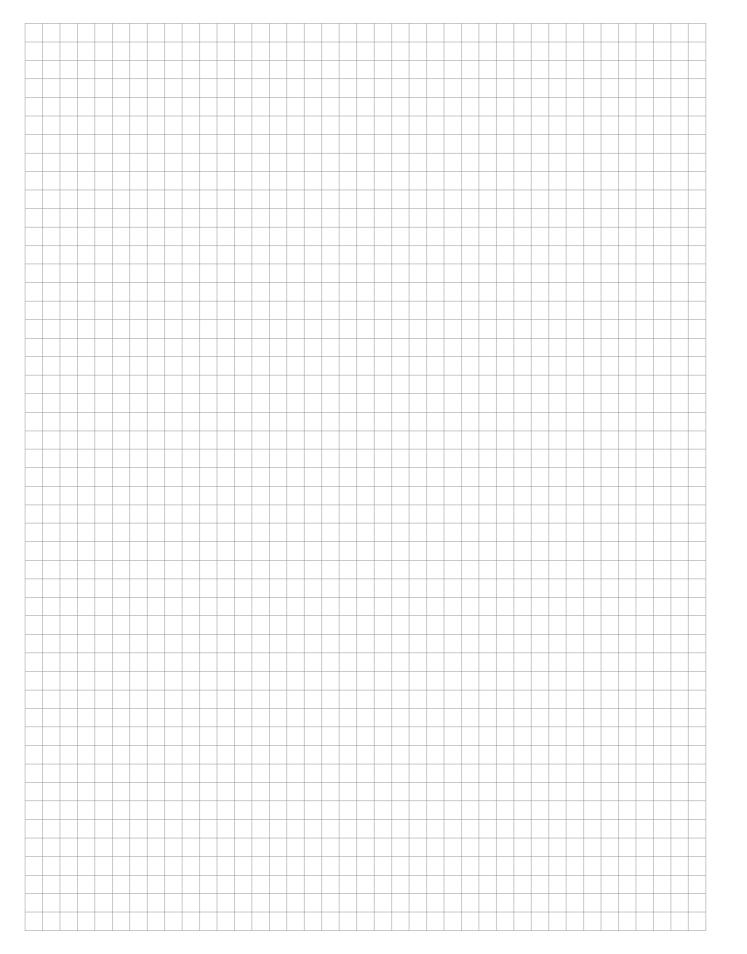
Code	Φd1/Φd2 Shaft diameter	ΦD	L	L1	F	E	Twisting moment M	ax. angular displacen	nent Max. speed S	Screw (M	) Material
ECS27/16A 0000	4 5 6 6.35(A1) 8	16	27	8.5	3	9.5	0.5N.m	2°	6000r/min	M3	AL-alloy
ECS29/20A	5 6 6.35(A1) 8 9.525(A2) 10 12	20	29	8.5	3	12.5	0.6N.m	2°	6000r/min	M3	AL-alloy
ECS34/25A	6 6.35(A1) 8 9.525(A2) 10 12	25	34	10.5	4	15	1.7N.m	2°	6000r/min	M4	AL-alloy
ECS38/32	6 8 9.525(A2) 10 12	32	38	11.5	4	21	1.7N.m	2°	6000r/min	M4	AL-alloy
ECS49/32	6 8 9.525(A2) 10 12	32	49	11.5	4	21	1.7N.m	2°	6000r/min	M4	AL-alloy
ECS51/40 0000	10 11 12 14 15 16	40	51	12.5	4.5	27	3.5N.m	2°	6000r/min	M5	AL-alloy
ECS57/55A 0000	12 14 15 16	50	57	13.5	5	40	9.0N.m	2°	6000r/min	M6	AL-alloy

## **Coupling Dimensions**









## Miniature Absolute Singleturn Encoder EAC50



Description Miniature absolute singleturn encoder EAC50 series can withstand a higher axial and radial load with its reasonable and compact structure. The standard flange combined the clamping and synchronous flanges together, while leaving multiple types of pre-screwed holes for easy installation. The EAC50 series can be widely used in angular and positioning measurement, particularly in the textile industry.

### Features

#### Mechanical Characteristics

shaft diameter (mm)	Ф6g6/Ф8g6	
Protection acc. to EN 60529	lp64	
Speed (r/m)	6000	
Max load capacity of the shaft		
Axial load capacity	40N	
Radial load capacity	80N	
Shock resistance	50G/11ms	
Vibration resistance	10G 10~2000Hz	
Bearing life	10 <sup>9</sup> revolution	
Rotor moment of inertia	1.8×10 <sup>-6</sup> kgm <sup>2</sup>	
Starting torque	<0.01Nm	
Body material	AL-alloy	
Housing material	AL-alloy	
Operating temperature	-20 °C~~+80 °C	
Storage temperature	-25 ℃~~+85 ℃	
Weight	330g	

Resolution

2, 4, 8, 16, 32, 64, 90, 128, 180, 250, 256, 360, 500, 512, 720, 1024

## **Electrical Characteristics**

Output circuit	PNP	PNP open collector	NPN	NPN open collector
Resolution	10 Bits	10 Bits	10 Bits	10 Bits
Supply voltage (Vdc)	10-30V/5V	10-30V/5V	10-30V/5V	10-30V/5V
Power consumption (no load)	≤125mA	≤125mA	≤80mA	≤80mA
Permissible load (channel)	±80mA	±80mA	±50mA	±50mA
Pulse frequency	Max300kHz	Max300kHz	Max300kHz	Max300kHz
Signal level high	MinUb-1.5V	MinUb-1.5V	MinUb-2.5V	MinUb*70%
Signal level low	Max0.4V	depends on pull-down resistor	Max0.4V	Max0.4V
Rise timeTr	Max 1 µs	Max 1 µs	Max 1µs	Max 1µs
Fall timeTf	Max 1 µs	Max 1 µs	Max 1µs	Max 1 µs

\*): NPN open collector is depending on the pull-up resistor. 4.7kΩ is the recommended resistance. 8.2kΩ is the recommended resistance for PNP open collector.

\*\*): NPN (PNP) open collector is depending on pull-up (down) resistor and cable length



- Pre-screwed holes for easy installation
- Clamping and synchronous flanges combined
- Durable stainless steel shaft
- Metal housing for shock resistance
- Waterproof metal wiring for greater IP level
- Protection class IP64
- Reverse connection protection

## Miniature Absolute Singleturn Encoder EAC50

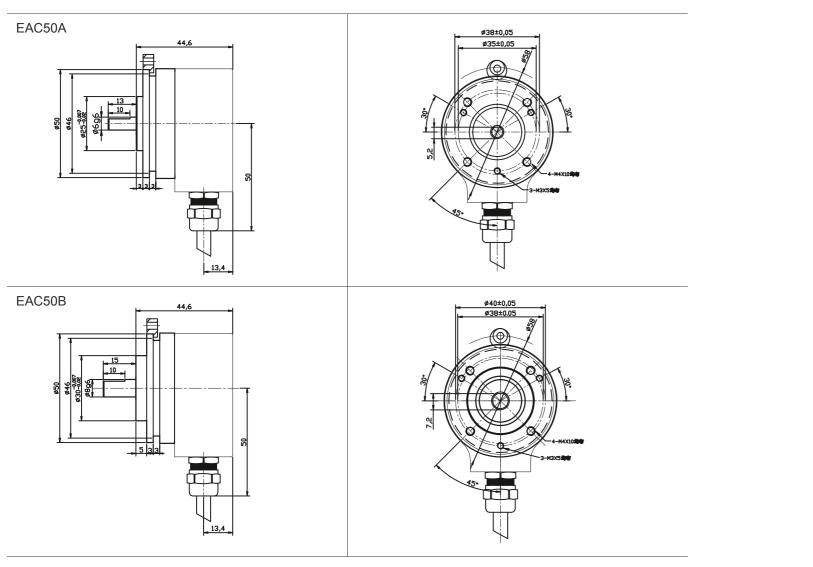
#### Terminal Configuration

Signal	0V	+Ub	bit0	bit1	bit2	bit3	bit4	bit5	bit6	bit7	bit8	bit9	V/R*
Color Code	WH	BN	GN	YE	GY	PK	BU	RD	BK	PL	GY/PK	RD/BU	YE/BN
Gray code	/	/	0	1	2	3	4	5	6	7	8	9	-

Attention

Bite definition of parallel interface for an absolute encoder is: bit0=MSB, bit1=MSB-1, bit2=MSB-2, .....

#### Dimensions



## Miniature Absolute Singleturn Encoder EAC50

\_

Shaft diameter

6=Ф6mm(ECAS50A) 8=Ф8mm(ECAS50B)

Flange type

Housing dimensions

50= housing dimensions

A=round flangeΦ25 mm

B=round flangeΦ30 mm

G

ſ

Order Code:

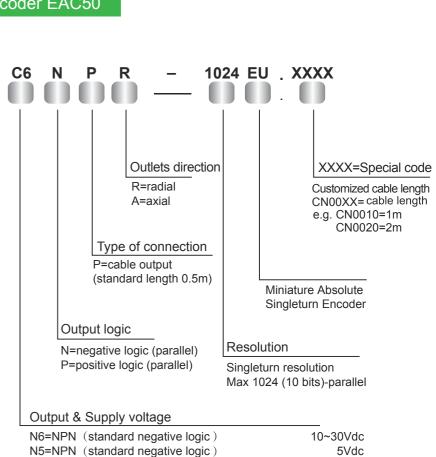
EAC 50 B 8

Series

EAC=absolute singleturn

servo-restraint ring: 50PXL (see installation accessories for reference)





	10 00000
N5=NPN (standard negative logic)	5Vdc
C6=NPN open collector (standard negative logic)	10~30Vdc
C5=NPN open collector (standard negative logic)	5Vdc
R6=PNP ( standard positive logic )	10~30Vdc
R5=PNP (standard positive logic)	5Vdc
U6=PNP open collector ( standard positive logic )	10~30Vdc
U5=PNP open collector ( standard positive logic )	5Vdc

Output code type

G=Gray Code

B=Binary

### Profibus-DP Interface Absolute Singleturn Encoder EAC58



#### Description

Profibus-DP interface absolute singleturn encoder EAC58 series provides outstanding performance in withstanding mechanical damages and higher axial and radial loads. Various types of flanges are available to meet different requirements. The series complies with Profibus protocol, and its maximum resolution is up to 8192. Its high speed communication and anti-interference deliver strong and stable operation.

#### Features

- Various types of flanges are available
- · Pre-screwed holes are convenient for installation
- · Waterproof seal provides greater IP level
- · Direct cable output, which is convenient for installation and maintenance
- Protection class IP65

## Mechanical Characteristics

 Metal housing for better shock resistance Conforming to Profibus-DP protocol

Shaft diameter (mm)         Ø6g6         -58B           Ø8g6         -58A/B           Ø9.52(3/8")g6         -58A           Ø10g6         -58C           Ø10g6         -58C           Hollow shaft diameter (mm)         Ø8H7/Ø9.52H7/Ø10H7           Ø12H7/Ø14H7/ Ø15H7         -58/W           Protection acc. to EN 60529         IP65           Speed         6000, continuous           Axial load capacity         80N           Radial load capacity         160N           Shock resistance         50G/11ms           Vibration resistance         10G 10~2000Hz           Bearing life         10 <sup>9</sup> revolution           Rotor moment of inertia         approx.1.8×10 <sup>-6</sup> kgm <sup>2</sup> Starting torque         <0.05Nm           Body material         ALUNI 9002/5 - (D11S)           Housing material         ALUNI 9002/5 - (D11S)           Operating temperature         -45° C~~+88°C           Weight         ~800g		
	Shaft diameter (mm)	Ф6g6 -58B
		Ф8g6 -58A/B
Hollow shaft diameter (mm)          Φ8H7/Φ9.52H7/Φ10H7 -58/W         Φ12H7/Φ14H7/ Φ15H7 -58/W          Protection acc. to EN 60529       IP65         Speed          6000, continuous          Axial load capacity          80N          Radial load capacity          160N          Shock resistance          50G/11ms          Vibration resistance          10G 10~2000Hz          Bearing life          10 <sup>9</sup> revolution          Rotor moment of inertia          approx.1.8×10 <sup>-6</sup> kgm <sup>2</sup> Starting torque          <0.05Nm		Ф9.52(3/8")g6 -58A
Market Data Game <ul> <li></li></ul>		Ф10g6 -58C
Protection acc. to EN 60529IP65Speed6000, continuousAxial load capacity80NRadial load capacity160NShock resistance50G/11msVibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Hollow shaft diameter (mm)	Ф8H7/Ф9.52H7/Ф10H7 -58/W
Speed6000, continuousAxial load capacity80NRadial load capacity160NShock resistance50G/11msVibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm <sup>2</sup> Starting torque<0.05Nm		Φ12H7/Φ14H7/ Φ15H7 -58/W
Axial load capacity80NRadial load capacity160NShock resistance50G/11msVibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Protection acc. to EN 60529	IP65
Radial load capacity160NShock resistance50G/11msVibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Speed	6000, continuous
Shock resistance50G/11msVibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Axial load capacity	80N
Vibration resistance10G 10~2000HzBearing life10 <sup>9</sup> revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Radial load capacity	160N
Bearing life10° revolutionRotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Shock resistance	50G/11ms
Rotor moment of inertiaapprox.1.8×10 <sup>-6</sup> kgm²Starting torque<0.05Nm	Vibration resistance	10G 10~2000Hz
Starting torque<0.05NmBody materialALUNI 9002/5 -(D11S)Housing materialAL6060Flange materialALUNI 9002/5 -(D11S)Operating temperature-40° C~~+80° CStorage temperature-45° C~~+85° C	Bearing life	10 <sup>9</sup> revolution
Body material       ALUNI 9002/5 -(D11S)         Housing material       AL6060         Flange material       ALUNI 9002/5 -(D11S)         Operating temperature       -40° C~~+80° C         Storage temperature       -45° C~~+85° C	Rotor moment of inertia	approx.1.8×10 <sup>-6</sup> kgm <sup>2</sup>
Housing materialAL6060Flange materialALUNI 9002/5 -(D11S)Operating temperature-40° C~~+80° CStorage temperature-45° C~~+85° C	Starting torque	<0.05Nm
Flange material     ALUNI 9002/5 -(D11S)       Operating temperature     -40°C~~+80°C       Storage temperature     -45°C~~+85°C	Body material	ALUNI 9002/5 -(D11S)
Operating temperature     -40° C~~+80° C       Storage temperature     -45° C~~+85° C	Housing material	AL6060
Storage temperature -45°C~~+85°C	Flange material	ALUNI 9002/5 -(D11S)
	Operating temperature	-40°C~~+80°C
Weight ~800g	Storage temperature	-45°C~~+85°C
	Weight	~800g

Resolution 8192 4096

#### **Electrical Characteristics**

Resolution	8192 (13 bits)	
Supply voltage	10~30 Vdc	
Power consumption (no load)	300mA	
Baud rate	12 Mbaud	
Linearity	+/- 1/2 LSB	
Output frequency	Max 100 KHz	

#### Connection

OV     Ground       A     Profibus-DPline output (GN)       B     Profibus-DPline output (RD)       A     Profibus-DPline input (GN)       B     Profibus-DPline input (RD)	+V	Supply voltage(24 VDC)
B     Profibus-DPline output     (RD)       A     Profibus-DPline input     (GN)	0V	Ground
A Profibus-DPline input (GN)	A	Profibus-DPline output (GN)
	В	Profibus-DPline output (RD)
B Profibus-DPline input (RD)	A	Profibus-DPline input (GN)
	В	Profibus-DPline input (RD)

### Profibus-DP Interface Absolute Singleturn Encoder EAC58

Introduction Profibus-DP interface absolute singleturn encoder (Identification number 0x0CCA) comforms to the Profibus-DP standard as described on the European Standard EN 50170 Vol. 2. The encoders are designed according to "Profibus Profile for Encoders, Order No. 3062".

The Profibus-DP interface has the same maximum resolution and features (8192 position/revolution) of the stand-along version, and it also has the advantages of the Profibus-DP network. Through the Profibus-DP network is possible to:

- When operating normally, light goes off



## nternal interface Address DIP switch Terminal resistance DIP switch

nner port

Address DIP switch Bit 8 is used for changing counter

direction. Bit 1 to Bit 7 is used

to set up the encoder address

up to 126 addresses.

A Profibus network can accept

The Bus line is closed when the

two switches are switched ON

Inside of the encoder wiring box

Back cover of the encoder

74111CE

'Bus line input

Bus line output

ower supply 24VDC

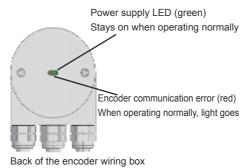
In this example, device's address is set up as 1001101, with the corresponding decimal address as 77. Bit 7 is the top digit, and bit 1 is the lowest digit. Bit 8 is used for changing the counter direction. Bit 1 to bit 7 are used to configuring encoder's address. Address setting Line close Example Line close

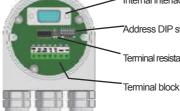


Network Characteristics Usually, an A type cable is used to wire a DP/FMS network. This cable has to have the following characteristics:

Parameter Character Rated cap Loop resis

Core diam Core cross kbaud Range/S







- During the periodic data exchange, obtaining the angular position from the encoder. - Resolution and the revolution are configurable now (please refer to the corresponding chapters for configuring the parameters).

- Changing the default increment count direction (change between CW/CCW when configuring the parameters).

- Perform the Preset operation (Set the encoder to read a specific position).

- Read the diagnosis status.

- Getting info about the code supplied by the device.

From the device it is possible to:

- Display the ON/OFF status.

- Display the device activity on the bus.

- Activate the Reset function

- Sett up the device address.

- If required, insert the terminal resistance into the bus.

- Change the counting direction

Installing the Profibus-DP encoder in a network requires the execution of the standard procedures necessary for configuring any Profibus-DP slave. The procesures are as follows: 1- Add the slave onto the master (please see corresponding chapter).

2- Wire the encoder into the Profibus network. Whether wiring it in the middle or at the terminal are depending on the physical position the device has in the bus.

3- Directly set up the address (which must be unique in the network and as the same as the device) for the slave.

4- Prepare the applications at the master side and set up the Profibus network.

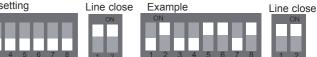
On the back cover of the encoder there are two LED indicators. The device's operating status can be observed by the two LEDs. The green LED shows the power status and must be on constantly. The red LED only switches off during the periodic data exchange between the Profibus master and the encoder.

Note: To set and configure the slave into the Profibus-DP master, it is necessary to

use the "gsd" file delivered with the encoder. The file can be found on the CD.

#### DIP-switch setup (configuring slave address)

Besides the address and the standard position of a terminal DIP switch, a configuration example of Profibus and the devices is illustrated below.



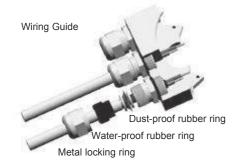
r	A type cable
ristic resistance (Ω)	135165 at a certain frequency (320Mhz)
pacity (PF/m)	<30
stance (Ω/Km)	<=110
neter (mm)	>0.64*)
s-section (mm <sup>2</sup> )	>0.34*)

This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows

.)										
	9.6	19.2	93.75	187.5	500	1500	12000			
Segment	1200m	1200m	1200m	1000m	400m	200m	100m			

Finally, the physical characteristics of a Profibus network are learned

## Profibus-DP Interface Absolute Singleturn Encoder EAC58



Max. number of station participating	DP: 126 (Address 0-125)
in the exchange of user data	FMS: 127 (Address 0-126)
Max. number of stations per segment	32
Available data transfer rates (kbit/s)	9.6, 19.2, 45.45, 93.75, 187.5, 500, 1500, 3000
Max. segments	6000,12000

According to EN50170, a maximum of 4 repeaters are allowed between any two stations.Dependent on the repeater type and manufacturer, more than 4 repeaters may be allowed in some cases. Refer to the manufacturer's technical specification for details.

### Wiring box

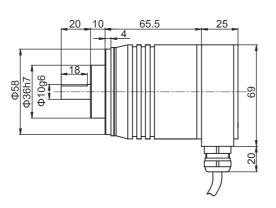
Unscrew the back cover, and wire the cables (power cable, input and output bus) according to the instructions on the cover. The cable will pass through the metallocking ring, water-proof rubber ring, and dust-proof rubber ring into the metal notch.Lock the metal ring to fasten the cables

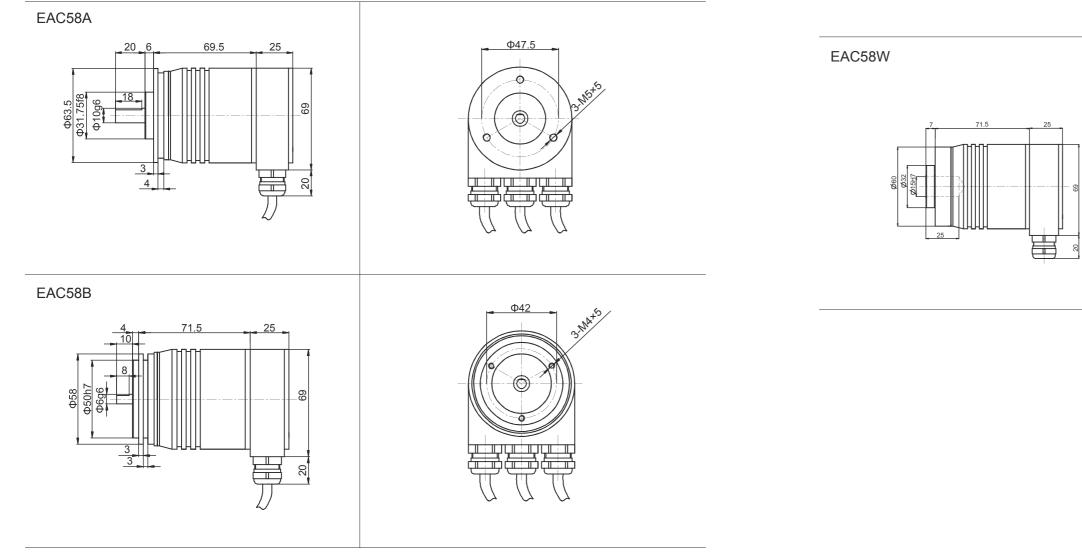
#### Dimensions



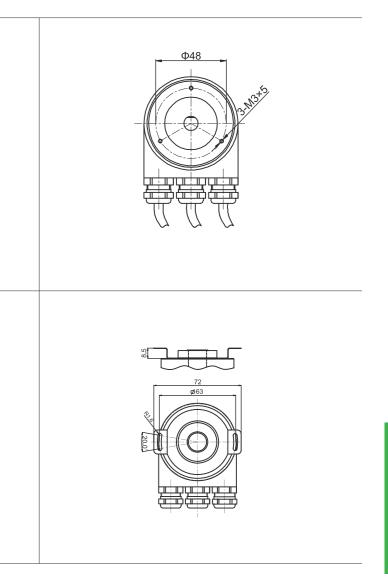
#### Dimensions

EAC58C



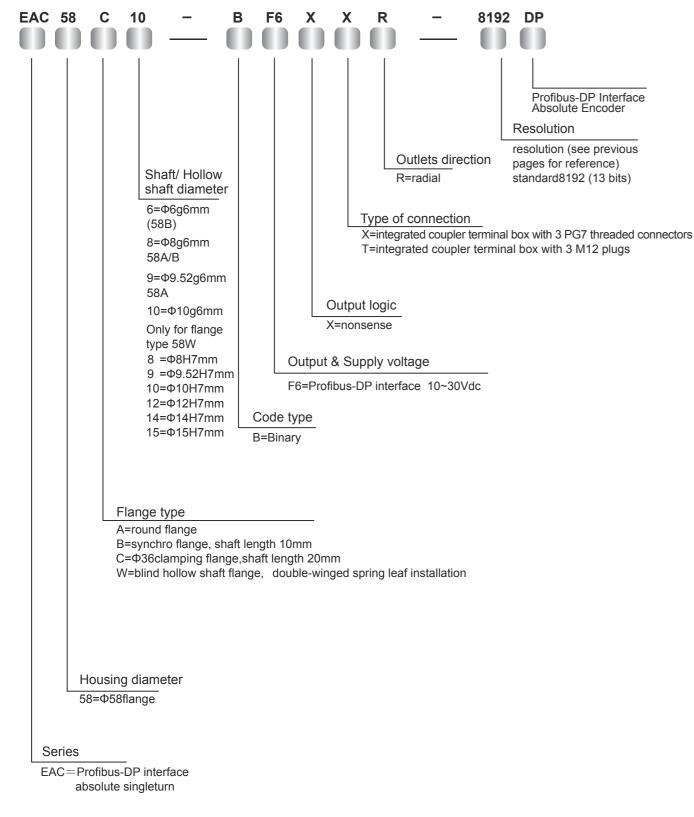






Profibus-DP Interface Absolute Singleturn Encoder EAC58

Order Code:



## 4...20mA Analog Output Absolute Singleturn Encoder EAC58



Description: The 4-20mA Analog output absolute singleturn encoder EAC58 series features acompact structure with striong perfomance in withstanding mechanical damages and higher axial and radial loads. EACA58 series is equipped with the RESET function, and has the resolution up to 8192.4-20mA output is compatible with special PC controllers.

## Features:

- **Mechanical Characteristics**

Shaft diameter (mm)	Ф6g6/0
Protection acc. to EN60529	IP65
Speed (r/m)	6000
Max load capacity of the shaft	
Axial load capacity	60N
Rsdial load capacity	120N
Shock resistance	50G/11
Vibration resistance	10G 1
Bearing life	10 <sup>9</sup> rev
Rotor moment of inertia	1.8×10
Starting torque	<0.01
Body material	AL-allo
Housing material	AL-allo
Operating temperature	-20°C
Storage temperature	-25°C⁄
Weight	360g

Resolution: 8192. For other resolution repuests please contact us for further information.

#### **Electrical Characteristics**

420mA	010V
1030VDC/5VDC	1030VDC
70mA	70mA
84mA	84mA
Max15.000/s	Max. 15.000/s
10 30VDC	10 30VDC
4 20mA	0 10V
200Ω	200Ω
0 360°	0 360°
0.2°	0.2°
13 Bit	13 Bit
Max. 2 ms	Max. 2 ms
0.1°/10K	0.1°/10K
≤3.5 mA	≤3.5 mA
	1030VDC/5VDC         70mA         84mA         Max15.000/s         1030VDC         420mA         200Ω         0360°         0.2°         13 Bit         Max. 2 ms         0.1°/10K

Conforms to CE requirements of EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3

- Waterproff seal provides greater IP level
- Pre-screwed holes for convenience purpose
- Durable stinless steel shaft
- Metal housing for better shock resistance
- Protection class IP65
- Staring and flnishing points calibration function equipped

## /Φ10h8 l1ms 10~2000Hz volution 0<sup>-6</sup>kgm<sup>2</sup> Nm loy loy ~~+80°C ;~~+85°C

## 4...20mA Analog Output Absolute Singleturn Encoder EAC58

#### **Terminal Configuration**

Voltage signal	0V	+Ub	VOUT+	VOUT-	VIN+	VIN-	STZ	VR	STT				÷
Current Signal	0V	+Ub			+	-	STZ	VR	STT				÷
Color	WH	BN	GN	YE	GY	PK	BU	RD	BK	VT	GY/PK	RD/BU	
Gray	1	2	3	4	5	6	7	8	9	10	1	12	PH

- +I: Input of current loop  $0V/+U_b$  and VIN+/VIN-: can be powered together or seperately
- VOUT+/VOUT-: voltage output VIN-/VOUT-: connected in circuit I-: Output of current loop
- STZ: SET input (signal level remains high for 2 sec), the output current is set to 4mA

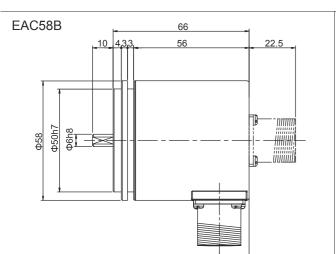
VR: Up/down input, as the input is activated, decreasing current values are transmitted when shaft turning clockwise

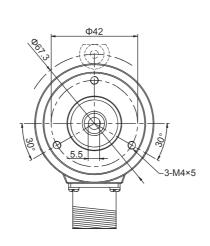
STT input: SET input (signal level remains high for 2 sec), the output current is set to 20mA

PH: Plug housing

- Attention: 1, Before initial start-up, unused outputs must be insulated.
  - 2, Shaft remains static, and at the same time set STZ & STT signal at high level; singleturn resumes to 4-20mA, and the present position output is at 4mA.

#### Dimensions

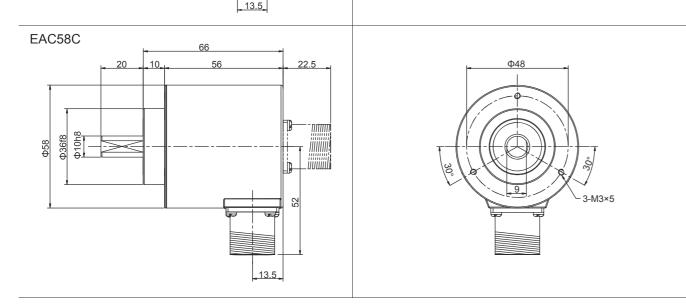


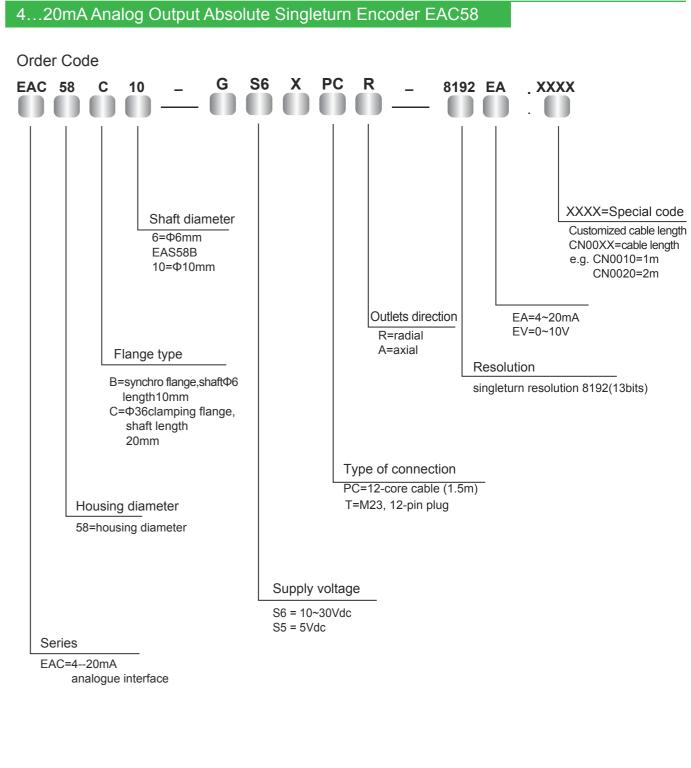


Top view of the connecting end

on needle connector block

12-pin plug







## Standard Absolute Singleturn Encoder EAC58



### Description

Standard absolute singleturn encoder EAC58 series can be widely used in various industrial environments. The series also has a good performance against mechanical damage, and withstanding higher axial and radial load. Various flange types and connections are available. EAC58 series also has the RESET function and resolution up to 8192.

#### Features

- · Pre-screwed holes for easy installation
- Waterproof seal provides greater IP level
- Durable stainless steel shaft
- Metal housing for shock resistanceMetal housing for shock resistance
- Protection class IP65
- Reverse connection protection and short circuit protection

#### **Mechanical Characteristics**

Shaft diameter (mm)	Φ6/Φ8/Φ9/Φ10h8
Protection acc. to EN 60529	lp65
Speed (r/m)	6000
Max load capacity of the shaft	
Axial load capacity	60N
Radial load capacity	120N
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000Hz
Bearing life	10 <sup>9</sup> revolution
Rotor moment of inertia	1.8×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.01Nm
Body material	AL-alloy
Housing material	AL-alloy
Operating temperature	-20 ℃~~+80 ℃
Storage temperature	-25 ℃~~+85 ℃
Weight	360g

Resolution

SSI: 1024, 2048, 4096, 8192

Parallel: 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096, 8192

### **Electrical Characteristics**

Output circuit	SSI	SSI	Parallel	Parallel
Output driver	RS422	RS422	Push-pull/NPN open collector	
Resolution	13 Bits	13 Bits	13 Bits	13 Bits
Supply voltage (Vdc)	10-30V	5V	10-30V	5V
Power consumption (no load)	≤200mA	≤200mA	≤200mA	≤200mA
Permissible load (channel)	±20mA	±20mA	±20mA	±2zhuo0mA
Pulse frequency	Max1MHz	Max1MHz	Max40kHz	Max40kHz
Signal level high	Typ.3.8V	Typ.3.8V	MinUb-2.8V	Min3.4V
Signal level low	Max0.5V	Max0.5V	Max2.0V	Max0.5V
Rise timeTr	Max 100ns	Max 100ns	Max 0.2µs	Max 0.2µs
Fall timeTf	Max 100ns	Max 100ns	Max 0.2µs	Max 0.2µs

## Standard Absolute Singleturn Encoder EAC58

## **Terminal Configuration**

SSI Wiring Guide

Signal	0V	+Ub	+C	-C	+D	-D	ST *	V/R <sup>*</sup>
Color Code	WH	BN	GN	YE	GY	ΡK	BU	RD
12-pin	1	2	3	4	5	6	7	8

### Parallel Wiring Guide

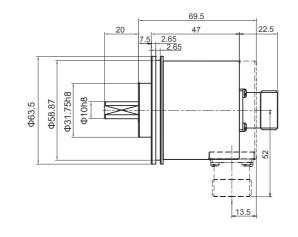
Signal	0V	+Ub	bit0	bit1	bit2	bit3	bit4	bit5
Color	WH	BN	GN	YE	GY	ΡK	BU	RD
17-pin	1	2	3	4	5	6	7	8
Gray	/	/	1	2	3	4	5	6
Binary								

Attention

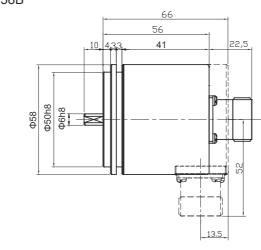
Bite definition of parallel interface for an absolute encoder is: bit0=MSB,bit1=MSB-1,bit2=MSB-2,.....

#### Dimensions

EAC58A

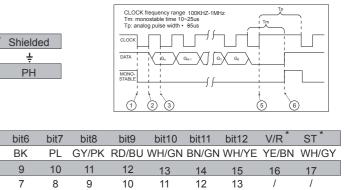




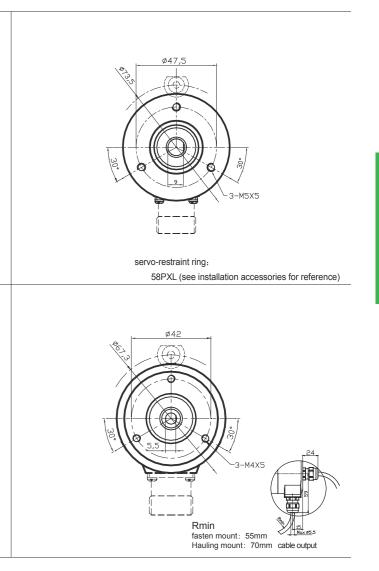




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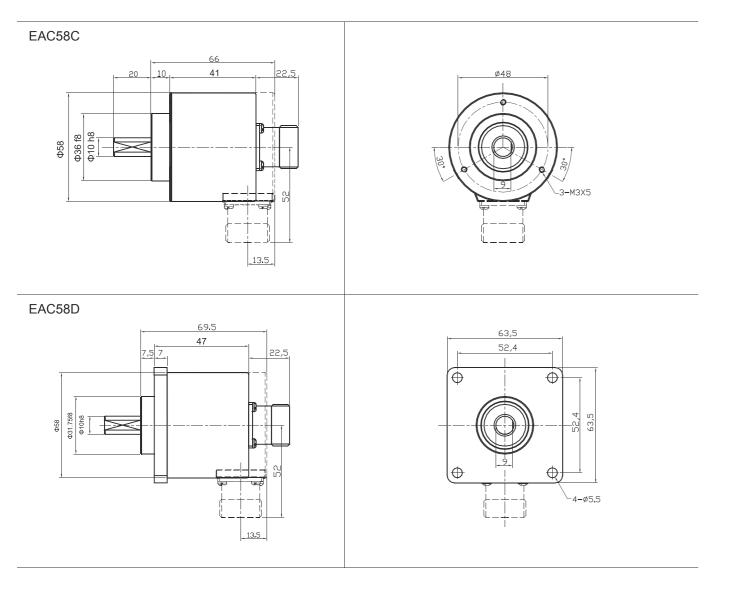


7



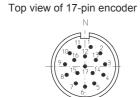
## Standard Absolute Singleturn Encoder EAC58

#### Dimensions



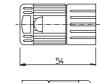
Note:Do not use excessive force during hardwiring between driving shaft,flange,and encoder to prevent shaft damage form overload.

Top view of 12-pin encoder





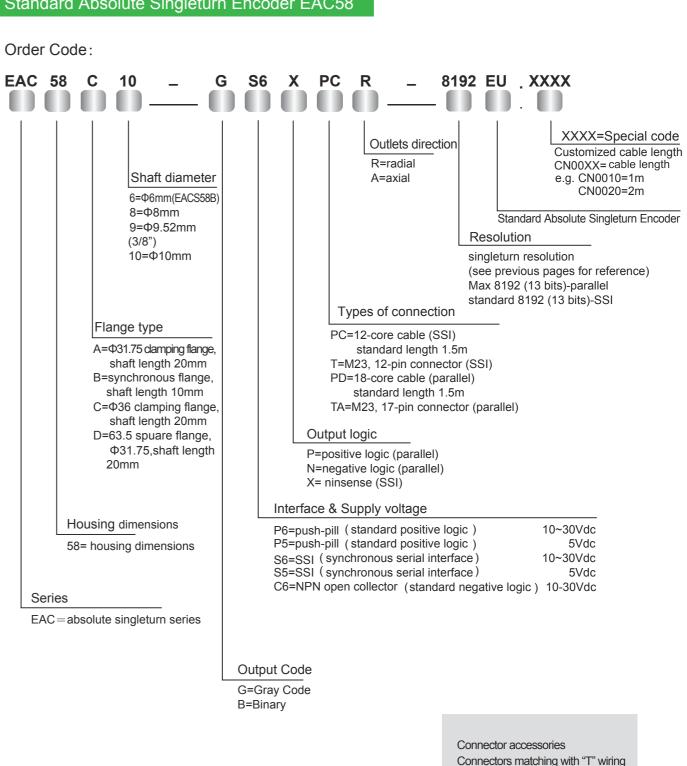
Hole arrangement for of 17-pin connector



Size



## Standard Absolute Singleturn Encoder EAC58





Connectors matching with "T" wiring Ordering code: TMSP1612F Connectors matching with "TA" wiring Ordering code: TMSP1617F

This sample is for reference only, please subject to the actual products. Please contact ELCO for further specification requests and requirements.

## Standard Hollow Shaft Absolute Singleturn Encoder EAC58P



#### Description

Standard absolute singleturn encoder EAC58P series can be widely used in various industrial environments. The series also has a good performance against mechanical damage, and withstanding higher axial and radial load. Various flange types and connections are available. EAC58P series is also equipped with the RESET function with resolution up to 8192.

#### Features

• Hollow shaft installation saves space with "C" ring lock

- +  $\Phi 8/10/12$  hollow shaft for easy applications
- Waterproof seal provides greater IP level
- · Metal housing is capable of withstanding higher axial and radial loads
- Protection class IP65
- Output cables or connectors are available for easy maintenance

### **Mechanical Characteristics**

Hollow shaft diameter (mm)	Ф8/Ф10/Ф12H7	
Protection acc. to EN 60529	IP65	
Speed (r/m)	6000	
Max load capacity of the shaft		
Axial load capacity	60N	
Radial load capacity	1200N	
Shock resistance	50G/11ms	
Vibration resistance	10G 10~2000Hz	
Bearing life	10 <sup>9</sup> revolution	
Rotor moment of inertia	1.8×10 <sup>-6</sup> kgm <sup>2</sup>	
Starting torque	<0.01Nm	
Body material	AL-alloy	
Housing material	AL-alloy	
Operating temperature	-20°C~~+80°C	
Storage temperature	-25°C~~+85°C	
Weight	360g	

Resolution

SSI: 1024, 2048, 4096, 8192 Parallel: 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096, 8192

#### **Electrical Characteristics**

Output circuit	SSI	SSI	Parallel	Parallel
Output driver	RS422	RS422	Push-pull/NPN OC	
Resolution	13 Bits	13 Bits	13 Bits	13 Bits
Supply voltage (Vdc)	10-30V	5V	10-30V	5V
Power consumption (no load)	≤200mA	≤200mA	≤200mA	≤200mA
Permissible load (channel)	±20mA	±20mA	±20mA	±20mA
Pulse frequency	Max1MHz	Max1MHz	Max40kHz	Max40kHz
Signal level high	Typ.3.8V	Typ.3.8V	Typ.Ub-2.8V	Typ.3.4V
Signal level low	Max0.5V	Max0.5V	Max2.0V	Max0.5V
Rise timeTr	Max 100ns	Max 100ns	Max 0.2µs	Max 0.2µs
Fall timeTf	Max 100ns	Max 100ns	Max 0.2µs	Max 0.2µs

## Standard Hollow Shaft Absolute Singleturn Encoder EAC58P

#### **Terminal Configuration**

#### SSI Wiring Guide

Signal	0V	+Ub	+C	-C	+D	-D	ST <sup>*</sup>	V/R*
Color	WH	BN	GN	YE	GY	ΡK	BU	RD
12-pin	1	2	3	4	5	6	7	8

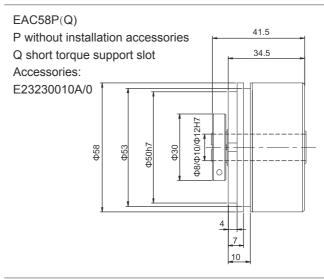
#### Parallel

Signal	0V	+Ub	bit0	bit1	bit2	bit3	bit4	bit5
Color	WH	BN	GN	YE	GY	ΡK	BU	RD
12-pin	1	2	3	4	5	6	7	8
Gray	/	/	1	2	3	4	5	6
Binary								

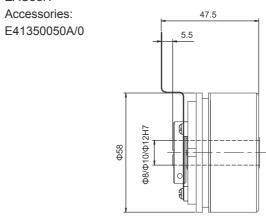
#### Attention

Bite definition of parallel interface for an absolute encoder is: bit0=MSB, bit1 =MSB-1, bit2=MSB-2,

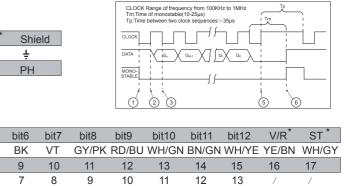
#### Dimensions

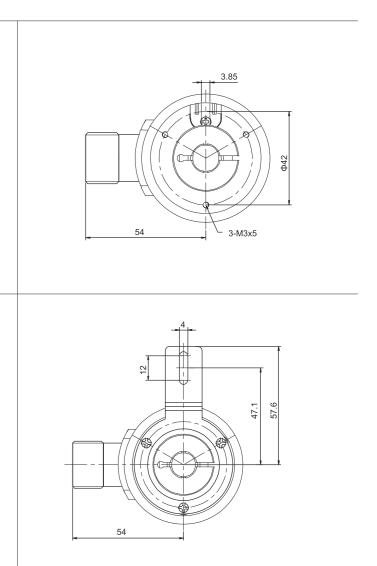


## EAC58H



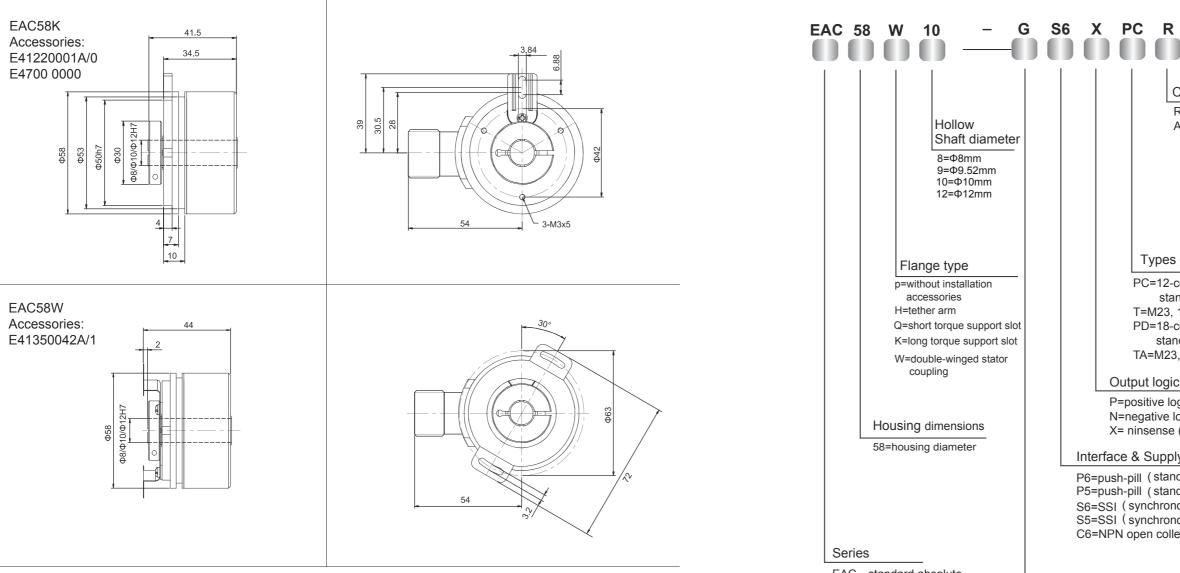






## Standard Hollow Shaft Absolute Singleturn Encoder EAC58P

### Mechanical Drawings



EAC=standard absolute singleturn

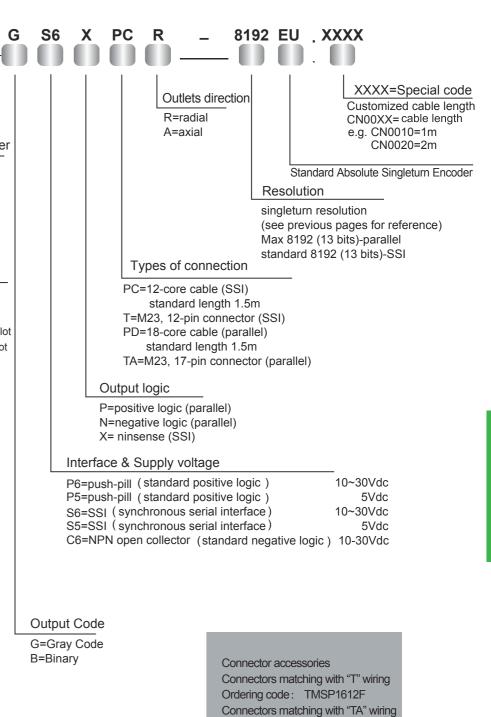
Order Code:

Output Code

G=Gray Code B=Binary



## Standard Hollow Shaft Absolute Singleturn Encoder EAC58P



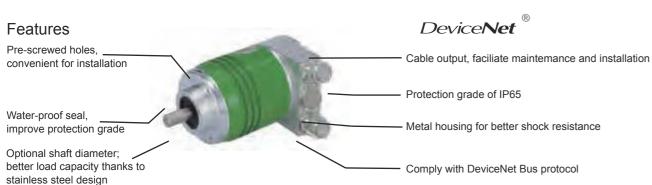
This sample is for reference only, please subject to the actual product. Please contact ELCO for further specification requests and requirements.

Ordering code: TMSP1617F

## DeviceNet Absolute Multiturn Encoder EAM58

#### Descriptions

DeviceNet absolute multituren encoder EAM58 series is used in various industrial environment. It delivers excellent performance in withstanding mechaniclal damages. It complies with DeviceNet protocol and has a max. resolution of 8192 and max. revolution up to 4096. Its high speed communication and anti-interference function ensure steady performance during operatuion.



4096 (Max. revolution) × 8192 (Max. resolution of single turn)

#### Mechanical Characteristics

Shaft diameter (mm)	Ф6д6	-58B optional
	Ф8д6	-58A/B/C
	Ф9.52(3/8")g6	-58A/B/C
	Ф10g6	-58A/B/ <b>C</b>
Hollow shaft diameter (mm)	Ф8H7/Ф9.52H7/Ф10H7	-58W
	Φ12H7/Φ14H7/ Φ15H7	-58W
Protection Grade	IP65	
Speed (r/m)	6000	
Axial load capacity	80N	
Radial load capacity	160N	
Shock resistance	50G/11ms	
Vibration resistance	10G 10~2000Hz	
Bearing life	10 <sup>9</sup> revolution	
Moment of inertia	approx. 1.8×10 <sup>-6</sup> kgm <sup>2</sup>	
Starting torque	<0.05Nm	
Housing material	AL UNI 9002/5 - (D11S)	
Cover material	AL 6060	
Flange material	AL UNI 9002/5 - (D11S)	
Operating temperature	-40°C~~+80°C	
Storage temperature	-45°C~~+85°C	
Weight	~800g	

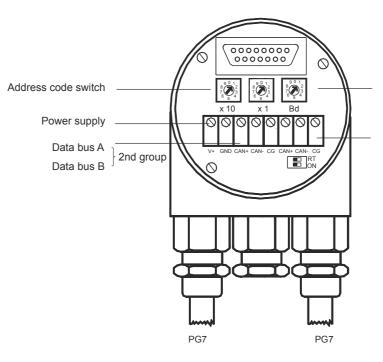
#### **Electrical Characteristics**

Max.revolution	4096 (12 bits)
Max revsolution/revolution	8192 (13 bits)
Supply voltage (Vdc)	10~30 Vdc
Power consumption (no load)	350mA
Bus Max. rate	500K
Linearity	+/- 1/2 LSB
Protocal	DeviceNet Profile for Encoder Release V2.0

#### **Terminal Assignment**

V+	Power supply (24VDC)			
GND	Power ground (24VDC)			
CG	CAN GND			
CAN-	CAN Low			
CAN+	CAN High			
CG	CAN GND			
CAN-	CAN Low			
CAN+	CAN High			

DeviceNet Absolute Multiturn Encoder EAM58



Regulate station address

The station address can be regulated by the swith and be distributed only once among the address 1 to 63.

x 10	x 1

#### Regulate Baud rate

Baud rate k bit/s	Switch
125	0
250	1
500	2



Baud rate code switch

Data bus A Data bus B 1st group

Regulate terminal resistor Set the terminal resistor (120  $\Omega$ ) into the circuit by the DIP switch.

Last station

RT



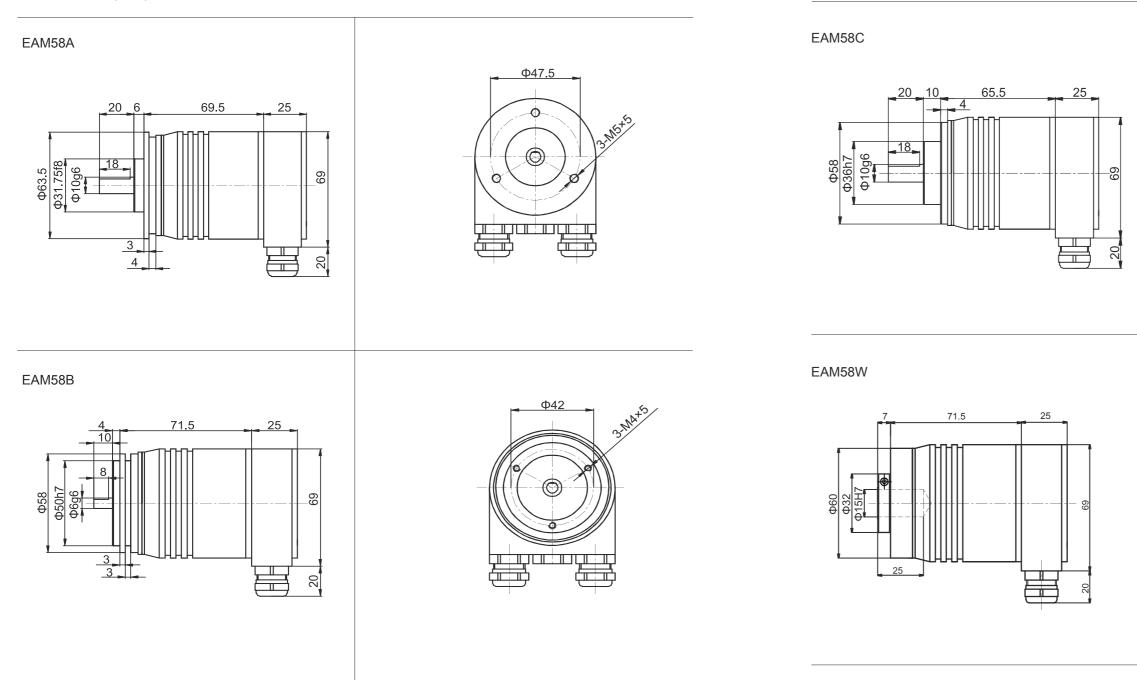
Station X

## DeviceNet Absolute Multiturn Encoder EAM58

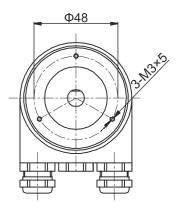
Dimensions (mm)

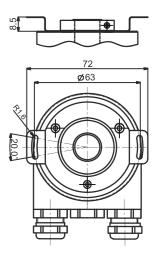
## DeviceNet Absolute Multiturn Encoder EAM58

Dimensions (mm)



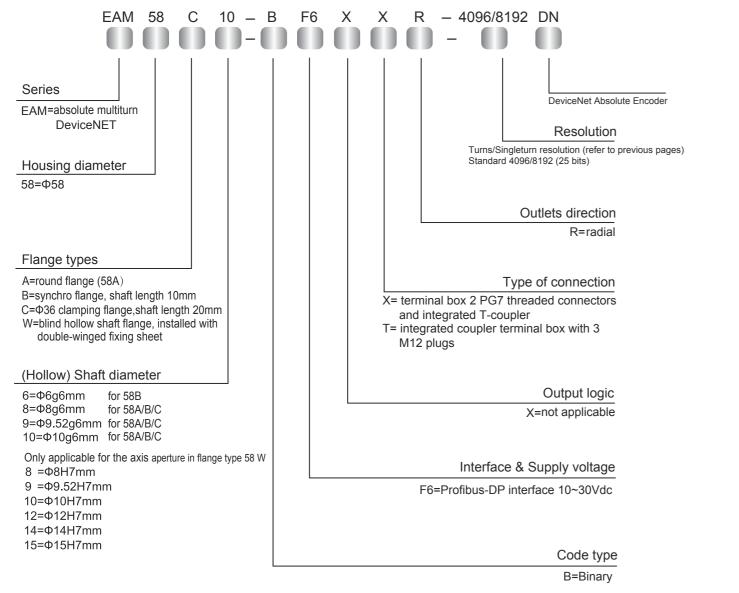






#### DeviceNet Absolute Multiturn Encoder EAM58

Order Code:



### M12 terminal assignment :

Bus in:

2	$\pm$ $^1$
3-+	
4	

Signal	DRAIN	+ V DC	- V DC	CAN_H	CAN_L
Pin	1	2	3	4	5

For 5-core male plug, the order code of "T" connector is: TMSP12F-F5

Bus out



Signal	DRAIN	+ V DC	-VDC	CAN_H	CAN_L
Pin	1	2	3	4	5

For 5-core female plug, the order code of "T" connector is: TMSP12F-M5

## Profibus-DP Interface Absolute Multiturn Encoder EAM58



Revolution and resolution can be programmed in PLC (see operation manual for

#### Electrical Characteristics

Revolution	4096 (12 bits)
Resolution/revolution	8192 (13 bits)
Supply voltage	10~30 Vdc
Power consumption (no load)	300mA
Baud rate	12 Mbaud
Linearity	+/- 1/2 LSB
Output frequency	Max 100 KHz
Terminal Assignament	

#### Terminal Assignement

+V	Supply voltage (24VDC)
0V	Ground
A	Profibus-DPline output (GN)
В	Profibus-DPline output (RD)
A	Profibus-DPline input (GN)
В	Profibus-DPline input (RD)



Profibus-DP interface absolute multiturn encoder EAM 58 series are capable of withstanding mechanical damage and higher axial and radial loads. Various types of flanges can be adapted to meet different requirements. It complies with Profibus protocol, and has the max resolution up to 8192 and the max revolution up to 4096. The resolution and revolution can be configured in accordance with customer requirements. Its high speed communication and anti-interference capabilities deliver stable operation.

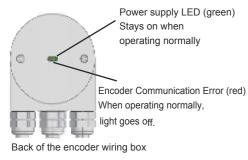
- · Various types of flanges available
- Pre-screwed holes for the convenience of customer
- Waterproof seal provides greater IP level
- · Cable output, convenient in installation and maintenance
- Protection class IP65
- Metal housing for better shock resistance
- · Conforming to Profibus-DP protocol, programmable revolution and resolution

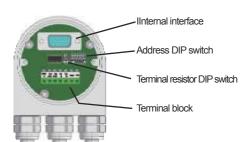
Ф6д6	-(58B)
Ф8д6	-58A/B/D/EA
Ф9.52(3/8")g6	-58A/D/E
Ф10g6	-58C
Ф8H7/Ф9.52H7/Ф10H7	-58W
<u>Φ12H7/Φ14H7/ Φ15H7</u>	-58W
IP65	
6000, continuous	
80N	
160N	
50G/11ms	
10G 10~2000Hz	
10 <sup>9</sup> revolution	
approx.1.8×10 <sup>-6</sup> kgm <sup>2</sup>	
<0.05Nm	
ALUNI 9002/5 -(D11S)	
AL6060	
ALUNI 9002/5 -(D11S)	
-40°C~~+80°C	
-45°C~~+85°C	
~800g -58B/C, 63A/D/E	
) ×4096 (resolution) or configurations)	

### Profibus-DP Interface Absolute Multiturn Encoder EAM58

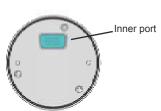
#### Introduction



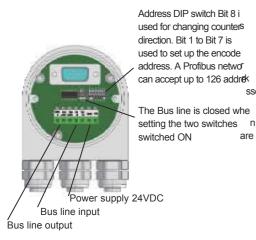




Inside of the encoder wiring box



Back cover of the encoder



- The Profibus-DP Bus multiturn absolute encoder (identification code 0x0CCA) conforms to the Profibus-DP standards as described in the European Standard EN 50170 volume 2. It also complies with the existing encoder regulation document: "Profibus Profile for Encoders, Order No. 3062" The Profibus-DP interface maintains the same maximum resolution and characteristics (8192 position/
- revolution, 4096 revolution) of the stand-along version, and it also adds on the extra feature of the Profibus-DP network.
- Through the Profibus-DP network, it is possible to:
- Obtain the angular position information from the encoder during the periodic data exchange.
- Program the resolution and the revolution (refer to corresponding chapters for parameter setting).
- Change the default increment counting direction (switch between CW/CCW when configuring the parameters).
- Perform the Preset operation (Set the encoder to read a specific position).
- Read the diagnosis status.
- Obtain info about the code supplied by the device.
- When using the device, it is possible to:
- Display the ON/OFF status.
- Display the device activity on the bus.
- Activate the Reset function
- Set up the device address
- If required, inserting the terminal resistor into the bus.
- Change the counting direction

Installation

Installing the Profibus-DP encoder in a network requires the execution of the standard procedures necessary for configuring any Profibus-DP slave. The procedures are as follows 1- Add the slave onto the master (please see corresponding chapter).

- 2- Wire the encoder into the Profibus network. Whether wiring it in the middle or at the
- terminal are depending on the physical position of the device in the bus.

3- Directly set up the address (which must be unique in the network and as same as the device) for the slave.

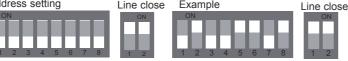
4- Prepare the applications at the master side and set up the Profibus network. On the back cover of the encoder there are two LED indicators. The device's operating status can be observed by the two LED. The green LED shows the power status and must be on constantly. The red LED only switches off only during the periodic data exchange between the Profibus master and the encoder.

Note: To set and configure the slave into the Profibus-DP master, it is necessary to use the "gsd" file delivered with the encoder. The file can be found on the CD.

#### DIP-switches setup (configuring slave address)

Besides the address and the standard position of a terminal DIP switch, a configuration example of Profibus and the devices is illustrated below.

In this example, device's address is set up as 1001101, with the corresponding decimal address as 77. Bit 7 is the top digit, and bit 1 is the lowest digit. Bit 8 is used for changing the counter direction. Bit 1 to bit 7 are used to configure encoder's address. Address setting Line close Example



#### Network Characteristics

are

Usually, an A type cable is used to wire a DP/FMS network. This cable has to have the following characteristics:

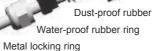
Rated capacity (PF/m)       <30         Loop resistance (Ω/Km)       <=110         S.       Core diameter (mm)       >0.64*)         Core cross-section (mm²)       >0.34*)         This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:			
Rated capacity (PF/m)       <30		Parameter	A type cable
Loop resistance (Ω/Km)       <=110		Characteristic resistance $(\Omega)$	135165at a certain frequency (320Mhz)
s.       Core diameter (mm) >0.64*)         Core cross-section (mm <sup>2</sup> ) >0.34*)         This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:		Rated capacity (PF/m)	<30
Core diameter (mm)       >0.64*)         Core cross-section (mm²)       >0.34*)         This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:	_		<=110
This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:	S.	Core diameter (mm)	>0.64*)
communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:		Core cross-section (mm <sup>2</sup> )	>0.34*)
communication speed allowed (12Mbaud). However, there are some limitations due to the maximum physical dimensions of a bus segment as follows:			
		communication speed allowed (12Mbaud).	However, there are some limitations due to the
		kbaud 96 192	•

maximan prijelear ann	0.10.01.0	a 200 00g						
kbaud	9.6	19.2	93.75	187.5	500	1500	12000	
Range/Segment	1200m	1200m	1200m	1000m	400m	200m	100m	

Finally, the physical characteristics of a Profibus network are now known.

## Profibus-DP Interface Absolute Multiturn Encoder EAM58

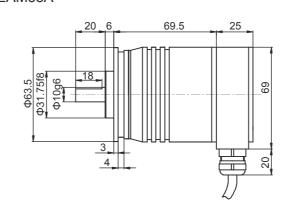




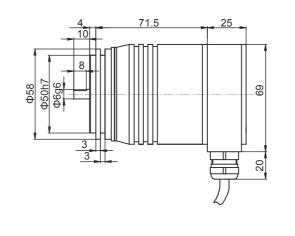
Wiring box

#### Dimensions





#### EAM58B

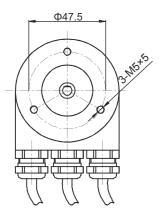




Max. number of station participating	DP: 126 (Address 0-125)
in the exchange of user data	FMS: 127 (Address 0-26)
Max. number of stations per segment	32
Available data transfer rates (kbit/s)	9.6, 19.2, 45.45, 93.75, 187.5, 500, 1500, 3000,
Max. segments	6000,12000
A	

According to EN50170, a maximum of 4 repeaters are allowed between any two stations. Dependent on the repeater type and manufacturer, more than 4 repeaters may be allowed in some cases. Refer to the manufacturer's technical specification for details.

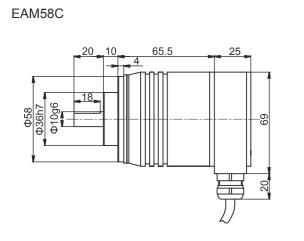
Unscrew the back cover and wire the cables (power cable, input and output bus) according to the instructions on the cover wiring. The cable will pass through the metal locking ring, water-proof rubber ring, and dust-proof rubber ring into the metal notch. Lock the metal ring to fasten the cables

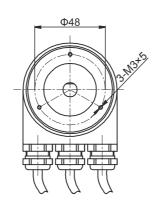


 $\bigcirc$ 

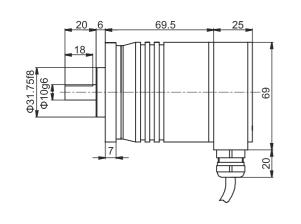
## Profibus-DP Interface Absolute Multiturn Encoder EAM58

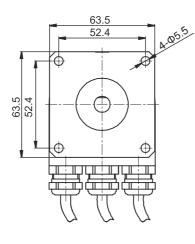
#### Dimensions

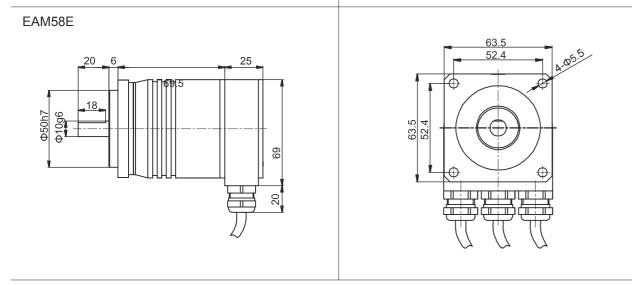




EAM58D

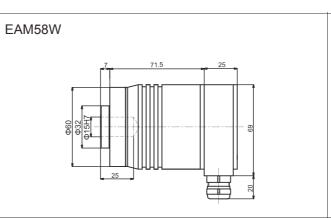




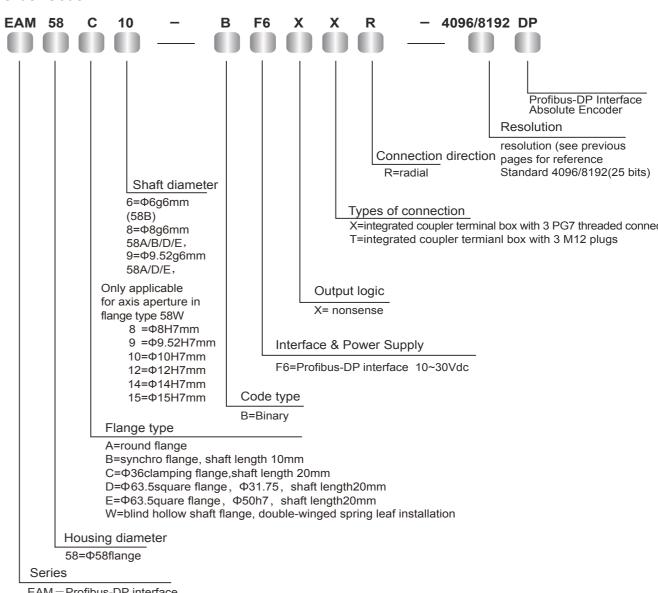


## Profibus-DP Interface Absolute Multiturn Encoder EAM58

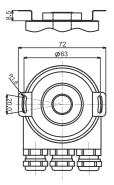
Dimensions



Order Code:







X=integrated coupler terminal box with 3 PG7 threaded connectors

## 4-20mA Analog Output Absolute Multiturn Encoder EAM58



#### Description:

4-20mA Analog output absolute multiturn encoder EAM58 series, designed with compact structure is capable of withstanding higher axial and radial loads. European standard flanges provide great convenience in installation. The encoder can provide 16 bits and 4-20mA analog and data outputs to meet the specific interface needs of PC. Multiple configurations of resolution and number of turns are available to meet different application requirements.

#### Features:

- European standard flange
- Waterproof seal provides greater IP level
- Pre-screwed holes for convenience purpose
- Durable stainless steel shaft
- Metal housing for better shock resistance
- Protection class IP65
- · Output cables or connectors are available for easy installation and maintenance
- · 4-20mA Analog output

#### Mechanical Characteristics

Shaft diameter(mm)	Ф6q6/Ф8q6/Ф9q6/Ф10q6
Protection acc. to EN 60529	IP65
Speed(r/m)	6000
Max load capacity of the shaft	
Axial load capacity	80N
Radial load capacity	160N
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000Hz
Bearing life	10 <sup>9</sup> revolution
Rotor moment of inertia	1.8×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.01Nm
Body material	AL-alloy
Housing material	AL-alloy
Operating temperature	-40°C~~+80°C
Storage temperature	-45°C~~+85°C
Weight	360g~750g

Resolution 256 512 1024 2048 4096 8192

others on request

#### **Electrical Characteristics**

Output circuit	420mA	010V
Supply voltage(Ub)	1030VDC/5VDC	1030VDC
Power consumption typ.	70mA	70mA
No load Max.	84mA	84mA
Word change frequency	Max15.000/s	Max. 15.000/s
Current loop supply voltage	10 30VDC	10 30VDC
Analogue signal	4 20mA	0 10V
Max. input resistance	200Ω	200Ω
Measuring range	Determined based on on actual resolution	Determined based on on actual resolution
Max. sensitivity (25°C)	0.2°	0.2°
Resolution	16 Bit	16 Bit
Building up time	Max. 2 ms	Max. 2 ms
Temperature coefficient	0.1°/10K	0.1° /10K
Power consumption (no load)	≤3.5 mA	≤3.5 mA

Sensors must be electrically insulated from current loop.

Conforms to CE requirements: EN 61000-6-1, EN 61000-6-4 and EN 61000-6-3

## 4-20mA Analog Output Absolute Multiturn Encoder EAM58

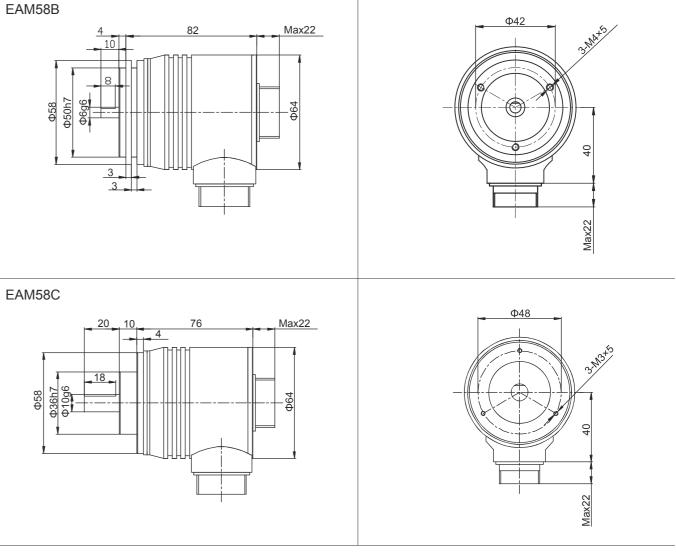
### **Terminal Configuration**

Voltage signal	0V	+Ub	VOUT+	VOUT-	VIN+	VIN-	STZ	VR	STT				÷
Current Signal	0V	+Ub			+	-	STZ	VR	STT				÷
Color	WH	BN	GN	YE	GY	PK	BU	RD	ΒK	VT	GY/PK	RD/BU	
Gray	1	2	3	4	5	6	7	8	9	10	1	12	PH

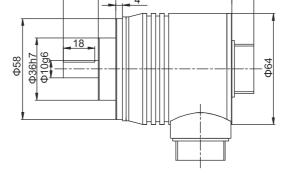
+I: Input of current loop  $0V\!/\!+\!U_b$  and VIN+/VIN-: can be powered together or seperately VOUT+/VOUT-: voltage output VIN-/VOUT-: connected in circuit I-: Output of current loop STZ: SET input (signal level remains high for 2 sec), the output current is set to 4mA VR: Up/down input, as the input is activated, decreasing current values are transmitted when shaft turning clockwise STT input: SET input (signal level remains high for 2 sec), the output current is set to 20mA PH: Plug housing

- Attention: 1, Before initial start-up, unused outputs must be insulated...
  - 2. Shaft remains static, and at the same time set STZ & STT signal at high level; singleturn resumes to 4-20mA, and the present position output is at 4mA.

### Dimensions







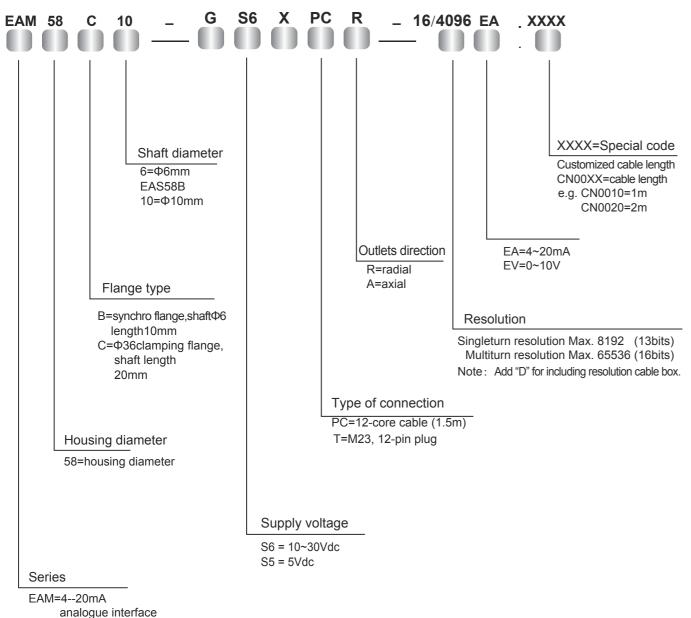


Top view of the connecting end on needle connector block 12-pin plug



## 4-20mA Analog Output Absolute Multiturn Encoder EAM58

### Order Code



## Standard Absolute Multiiturn Encoder EAM58

#### Descriptions

### Features

### Mechanical Characteristics

_		
	Shaft diameter (mm)	Φ
	Hollow shaft diameter (mm)	Φ
Γ		Φ
	Protection Grade	IF
	Speed (r/m)	6
	Max. load capacity of the shaft	
Γ	Axial	8
	Radial	1
	Shock resistance	5
	Vibration resistance	1(
Γ	Bearing life	1
	Moment of inertia	1
	Starting torque	<
	Body material	Α
Γ	Housing material	A
	Operating temperature	-4
	Storage temperature	-4
	Weight	а

#### Regular resolution:

Turns available: 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096 Optional resolution per turn: 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096, 8192 ST: Reset input, the current position value is saved as the new "0" position. VR: Up/Down input, once this input is activated, the shaft will turn clockwise, and the output value will decrease gradually. Latch: Latch input, current output value is freezed.

#### **Electrical Characteristics**

Output circuit	SSI	SSI	Parallel	Parallel
Output and driver	RS422	RS422	Push-Pull	Push-Pull
Resolution	13 Bits	13 Bits	13 Bits	13 Bits
Supply voltage (Vdc)	10-30V	5V	10-30V	5V
Power consumption (no load)	≤200mA	≤200mA	≤200mA	≤200mA
Max. load current	±20mA	±20mA	±20mA	±20mA
Max.output frequency	Max.15kHz	Max.15kHz	Max.40kHz	Max.40kHz
Signal level high	Typ.3.8V	Typ.3.8V	Min.Ub-2.8V	Min.3.4V
Signal level low	Max.0.5V	Max.0.5V	Max.2.0V	Max.0.5V
Rise time Tr	Max 100ns	Max 100ns	Max 1µs	Max 0.2µs
Fall time Tf	Max 100ns	Max 100ns	Max 1µs	Max 0.2µs



The standard absolute multiturn encoder EAM58 series offers excellent performance to resist mechanical shocks and is capable of withstanding high axial and radial loads. Various flange types provide great convenience for installation; serial and parrallel interfaces are provided for various upper PC; optional turns, resolutions and code formats greatly facilitate customer's application.

- Various types of flanges available
- Pre-screwed holes convenient to installation
- Metal housing to resist shocks
- Protection grade of IP65
- Waterproof seal provides higher IP grade
- Optional shaft diameters facilate the application Varioius turns and resolutions

Optional output connecting for easy use

#### Ф6g6/Ф8g6/Ф9g6/Ф10g6 Ф8H7/Ф9.52H7/Ф10H7 -58W Ф12H7/Ф14H7/ Ф15H7 -58W P65 6000 30N 160N 50G/11ms 10G 10~2000Hz 10<sup>9</sup> revolution I.8×10<sup>-6</sup>kgm<sup>2</sup> <0.01Nm Al-alloy Al-alloy 40°C~~+80°C 45°C~~+85°C approx. 400g

## Standard Absolute Multiiturn Encoder EAM58

## Terminal Assignment

SSI

Signal	0V	+Ub	+C	-C	+D	-D	ST *	V/R*	Latch	Shield
Color Code	WH	BN	GN	YE	GY	PK	BU	RD	BK	÷
12-pin	1	2	3	4	5	6	7	8	9	PH

CLOCK Range of frequency from 100KHZ to1MHz Tp Tm: time of monostable 10-25us Tp: time between two clock sequences• 85µs
DATA I Gn Gn Gn Gn G
MONO- STABLE

## Parallel

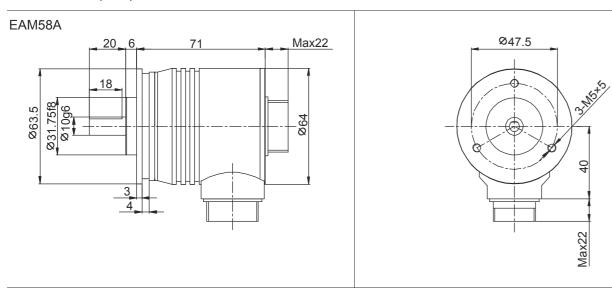
	VH/GN BN/GN WH/YE BN/YE WH/GY
M32-pin j h A B C D E F G H J	J K L M N
Gray / / G1 G2 G3 G4 G5 G6 G7 G8 G9	G9 G10 G11 G12 G13

Signal	bit13	bit14	bit15	bit16	bit17	bit18	bit19	bit20	bit21	bit22	bit23	bit24	Latch	V/R <sup>*</sup>	ST	
Color Code	BN/GY	WH/PK	BN/PK	WH/BU	BN/BU	WH/RD	BN/RD	WH/BK	BN/BK	GN/GY	YE/PK	GY/PK	YE/BK	RD/BU	GN/BU	
M32-pin	Р	R	S	Т	U	V	W	Х	Y	Z	а	d	е	g	f	
Gray	G14	G15	G16	G17	G18	G18	G20	G21	G22	G23	G24	G25	/	/	/	

Attention:

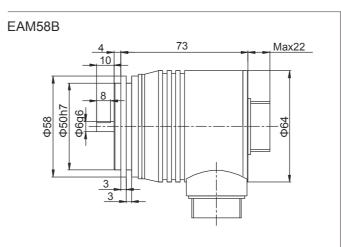
Bite definition of the parallel interface for an absolute encoder: bit0=MSB,bit1=MSB-1,bit2=MSB-2, .....

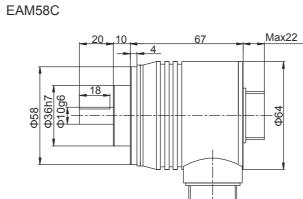
## Dimensions (mm)



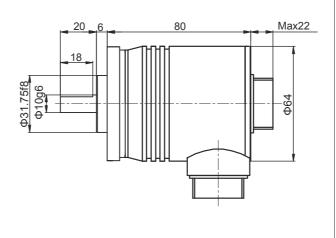
## Standard Absolute Multiturn Encoder EAM58

## Dimensions (mm)

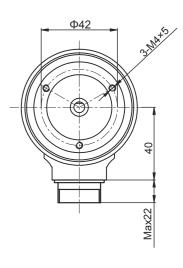


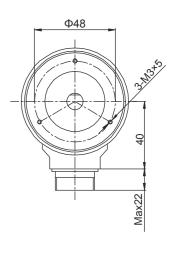


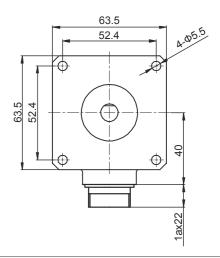






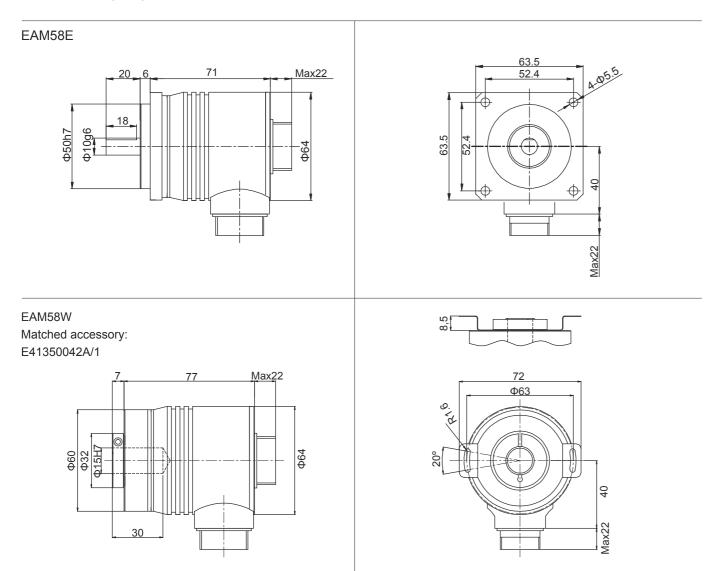


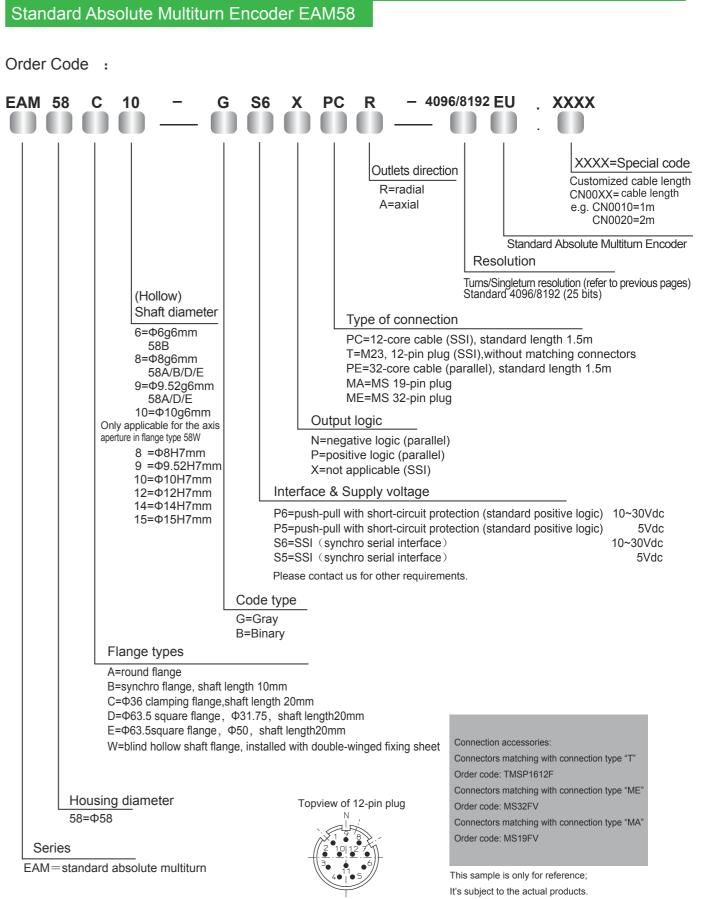




## Standard Absolute Multiturn Encoder EAM58

Dimensions (mm)







Connection accessories:
Connectors matching with connection type "T"
Order code: TMSP1612F
Connectors matching with connection type "ME"
Order code: MS32FV
Connectors matching with connection type "MA"
Order code: MS19FV

## ProfiNet Interface Absolute Multiturn Encoder EAM58



### Desctiption

The ProfiNet Interface Absolute Multitum Encoder EAM58 Series, has a good resistance to mechanical damage and is also capable of withstanding higher axial and radial loads. Various types of flanges can be used to meet different requirements. It complies with ProfiNet interface protocol and has a max. resolution of 8192 and a max. revolution of 4096. The resolution and revolution can be programmed according to customer requirements. The high speed communication and anti-interference features ensure steady performance during operation.

#### Features

- 6 Status indicators, for a fast and accurate understanding of the product status
- 3×M12 Connectors, implement a fast connection
- ProfiNet IO/RT interface with an intelligent diagnosis and high speed data transmission function
- Software configures the application of various parameters convenient maintenance
- Faster data update, update time ≤1ms

#### Mechanical Characteristics

Shaft Diameter(mm)	Ф6д6 -58В
	Ф10g6 -58C
Hollow Shaft Diameter(mm)	Ф8H7/Ф10H7/Ф12H7 -58W
Degree of Protection	IP65
Speed	6000
Axial load capacity	40N
Radial load capacity	80N
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000Hz
Bearing life	10 <sup>9</sup> revolution
Rotor moment of inertia	approx. 1.8×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.05Nm
Body material	AL UNI 9002/5 -(D11S)
Housing material	AL 6060
Flange material	AL UNI 9002/5 -(D11S)
Operating temperature	-40°C~~+80°C
Storage temperature	-45°C~~+85°C
Weight	~600g

## **Electrical Characteristics**

Max. number of laps	4096 (12 bits)
Max. resolution	8192 (13 bits)
Supply voltage	10~30 Vdc
Current consumption (without load)	200mA
Max. bus rate	100 Mbits/s
Linearity	12bits+/- 1/2 LSB
Interfaces	PROFINET IO/RT Class C
Encoder device protocol	V4.1 Class3

## ProfiNet Interface Absolute Multiturn Encoder EAM58

## LED indicator light

Power light:	Green light for bre
Configuration lamp:	Red light for break
Interface 1/2:	Green/orange ligh

Data port 1:

Signal	T×D+	R×D+	T×D-
Needle number	1	2	3

#### Data port:

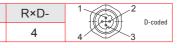
Signal	+V	_	-V	
Needle number	1	_	3	

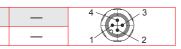
#### Data port 2:

Si	gnal	T×D+	R×D+	T×D-	
Ne	edle number	1	2	3	



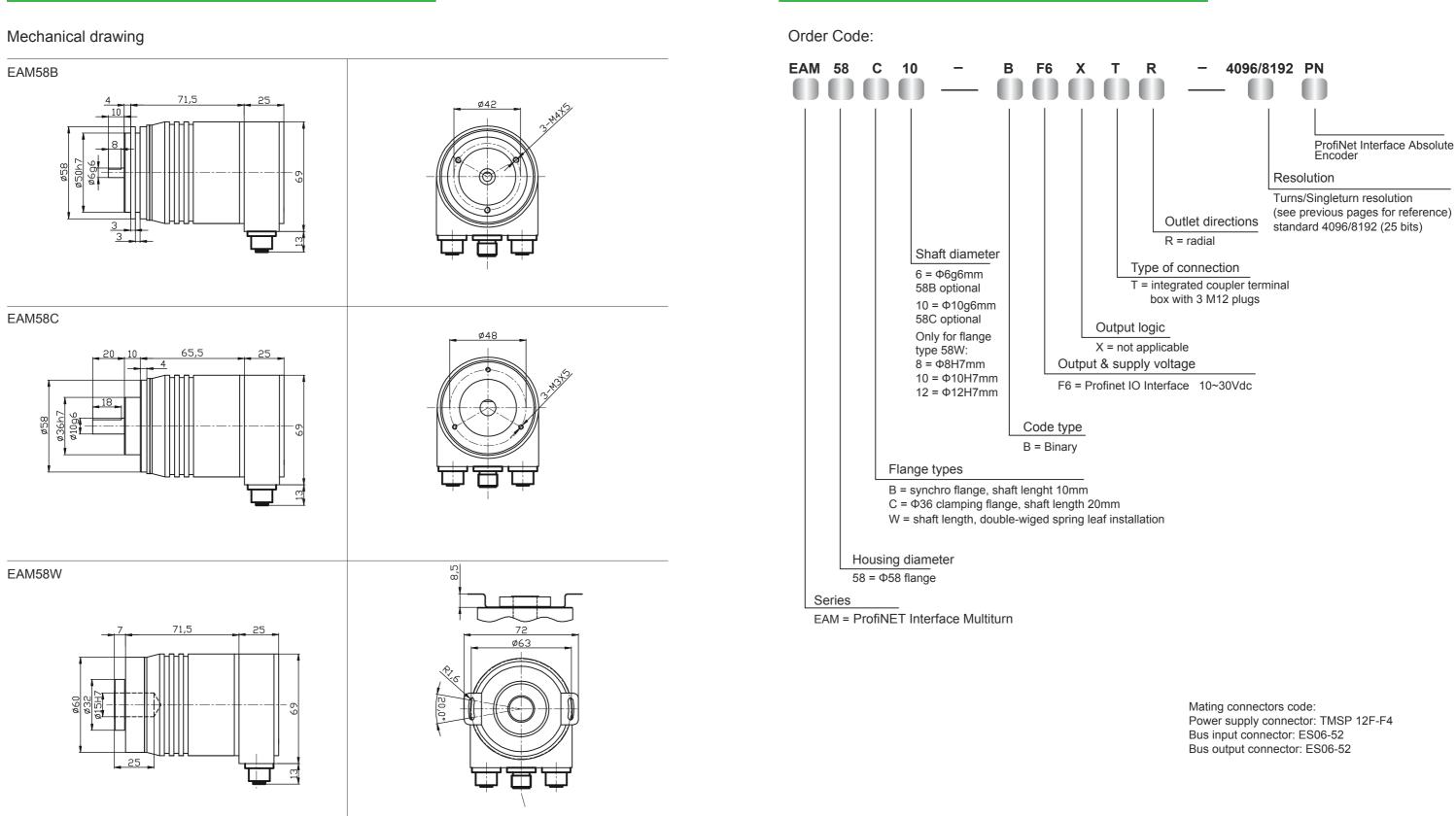
eakdown, no light for no power supply akdown, no light for normal configuration ht for normal work, no light for not normal





R×D-	12	D-coded
4	4 3	D-coueu

## ProfiNet Interface Absolute Multiturn Encoder EAM58





ProfiNet Interface Absolute Multiturn Encoder EAM58

### Large Hollow Shaft Profibus-DP Interface Absolute Multiturn Encoder EAM90L



#### Description

Profibus-DP interface absolute multiturn encoder EAM90L series delivers outstanding performance in withstanding mechanical damages higher axial and radial loads. Through-hole installations and various types of shatfs diameters could meet the different repuirements of customers. It complies with Profibus protocol and has a maximum resolution of 16384 and revolution of 4096. The resolution and revolution can be programmed on repuests. Its high speed communication and anti-interference performance ensure a steady operation.

#### Features

- · Waterproof seal provides greater IP level
- · Various types of stainless steel shafts diameters
- · Metal housing for better shock resistance
- Direct cable output, convenient for installation and maintenance
- Protection class IP65
- Conforming to the Profibus protocol Programmable revolution and resolution

### Mechanical Characteristics

Shaft diameter(mm)	Ф12H7/Ф15H7/Ф20H7//Ф24H7/Ф28H7/
	Ф(5/8)"H7/Ф1"H7/Ф12g6X30
Protection acc. to EN 60529	IP 65
Speed(r/m)	Max.6000 continuous Max.3000
Max load capacity of the shaft	
axial	40 N
radial	80 N
Shock resistance	2500 m/s <sup>2</sup> 6ms
Vibration resistance	100 m/s <sup>2</sup> 10~2000 Hz
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	~72 x 10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	hollow shaft < 0.2 Nm
	shaft < 0.05 Nm
Body material	AL-alloy
Housing material	AL-alloy
Operating temperature	-20°C ~ +80°C
Storage temperature	-25°C ~ +85°C
Weight	~ 900g

#### **Electrical Characteristics**

Supply voltage(+Ub)	10~30 V DC
Power consumption	Max.0.29 A
Linearity	± 1/2 LSB ( ± 1 LSB 13/14 bit) <sub>2</sub>
Interface	RS 485
Protocols	Profibus-DP, encoder profile class 2
Baud rate	Max. 12 Mbit/s
Address	programmable via DIP switches

Conforms to CE acc. to EN 61000-6-1. EN 61000-6-4 and EN 61000-6-3 Conforms to EMC acc. to EN 61000-4.5

Profibus Documentations for Programmable parameters: field bus Encoders:

- Please refer to PROFIBUS-DP Proportional factor for detailed information, i.e. DIN 19245-3 and EN 50170, and OVERVIEW for other information.
- Rotation Direction

  - Single turn resolution
  - Total resolution
  - Preset position
  - Diagnostic mode

Resolution

Encoder with integrated coupler:

LED Diagnostic Display

Achieving current isolation through Fieldus DC/DC converter

Including RS485 driver, max baud rate 12MB

Equipped with Class1 & Class 2 functions

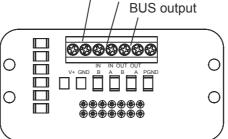
· Configure Fieldbus address through DIP switch

4096 (revolution) ×8192 (resolution) 4096 (revolution) ×4096 (resolution) Revolution and resolution are programmable in PLC (see operation manual for programming steps)

## Large Hollow Shaft Profibus-DP Interface Absolute Multiturn Encoder EAM90L



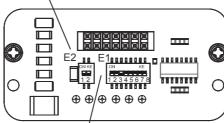
Order No. 3062"



**BUS** input

Terminal wiring block of an encoder

E2: Line close DIP switch — Default OFF DIP1-DIP2, the BUS is closed when setting the two switches ON.120 $\Omega$ .



E1: Address DIP switch-DIP1- DIP7 address setting switch, binary operation, the default address is 4 as illustrated in the diagram, a maximum number of 126 addresses are acceptable in Profibus network. DIP8: CW/CCW

#### Connection

V+	Supply voltage
GND	Ground
В	Profibus-DPline input (RD)
А	Profibus-DPline input (GN)
В	Profibus-DPline output (RD)
А	Profibus-DPline output (GN)

Rang

341



#### Introduction

- Profibus-DP interface absolute multiturn encoder (Identification number 0x0CCA) complies with the Profibus-DP standards as described on the European Standard EN 50170 volume 2. The encoders also conform to "Profibus Profile for Encoders,
- The Profibus-DP interface maintains the same maximum resolution (16384 position per revolution, 16384 revolutions) and the features of a stand-along unit with the bonus of the Profibus-DP network.
- Through the Profibus-DP network it is able to: - Obtain the angular position from the encoder
- during the periodic data exchange. - Program the resolution and revolution (refer to
- corresponding chapters for parameter setup).
- Change the default incremental direction (convert
- between CW/CCW during parameter setup). - Perform the Preset operation (program the
- encoder to read a specific position).
- Read the diagnostic status.
- Obtain info about the code came with the device.

#### Installation

- Installing the Profibus-DP encoder in a network requires the execution of a typical procedure necessary for configuring any Profibus-DP slave. The procedure is as follows 1- Commissioning the slave onto the master (see corresponding chapter).
- 2- Wiring the encoder into the Profibus network using the physical location of the device in the bus.
- 3- Configuring slave's address (which must be unique in the network and the same as the device)
- 4- Preparing applications from the master and setting up the Profibus networ On the back cover of the encoder there are two LED indicators. The device's operating status can be observed by the two LED. The green LED shows the power status and must be on constantly. The red LED only switches off during the periodic data exchange
- between the Profibus master and the encoder. Note: To set and configure the slave into the Profibus-DP master it is necessary to use the "gsd" file delivered with the encoder. The file can be found on the CD.

### DIP-switches setup (configuring slave address)

- Besides the address and the standard position of a terminal DIP switch, a configuration example of Profibus and the devices is illustrated below: In this example, device's address is set up as 1001101, with the corresponding decimal address as 77. Bit 7 is the top digit, and bit 1 is the lowest digit Bit 8 is used for changing
- the counter direction. Bit 1to bit 7 are used to configure encoder's address Address setting Line close Line close Example• •



## **Network Characteristics**

Usually, an A type cable is used to wire a DP/FMS network. This cable has to have the following characteristics.

Parameter	A type cable
Characteristic resistance $(\Omega)$	135165at a certain frequency (320Mhz)
Rated capacity (PF/m)	<30
Loop resistance (Ω/Km)	<=110
Core diameter (mm)	>0.64*)
Core cross-section (mm <sup>2</sup> )	>0.34*)

This cable allows the optimal network utilization. In fact, it is possible to reach the maximum communication speed allowed (12Mbaud). However, there are some

limitations due to the maximum physical dimensions of a bus segment as follows							
kbaud	9.6	19.2	93.75	187.5	500	1500	12000
Range/Segment	1200m	1200m	1200m	1000m	400m	200m	100m

Finally, the physical characteristics of a Profibus network are now known.



With the device's class, it is able to:

- TDisplay the ON/OFF status.

- Configure the device address.

- Change the counting direction

- If required, inserting the terminal

on the bus

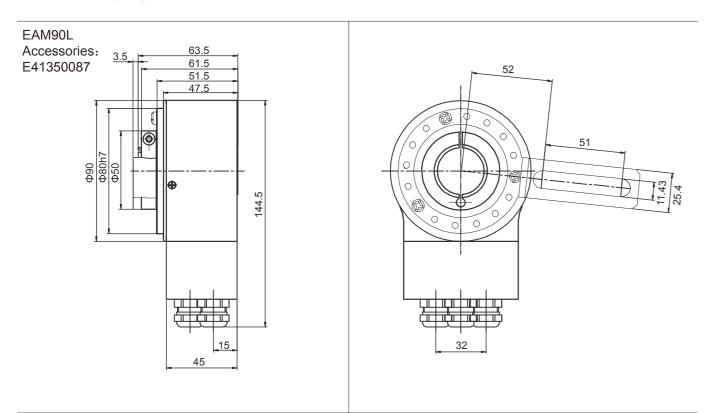
- Reset function

resistor into the bus.

- Display the BUS device activity

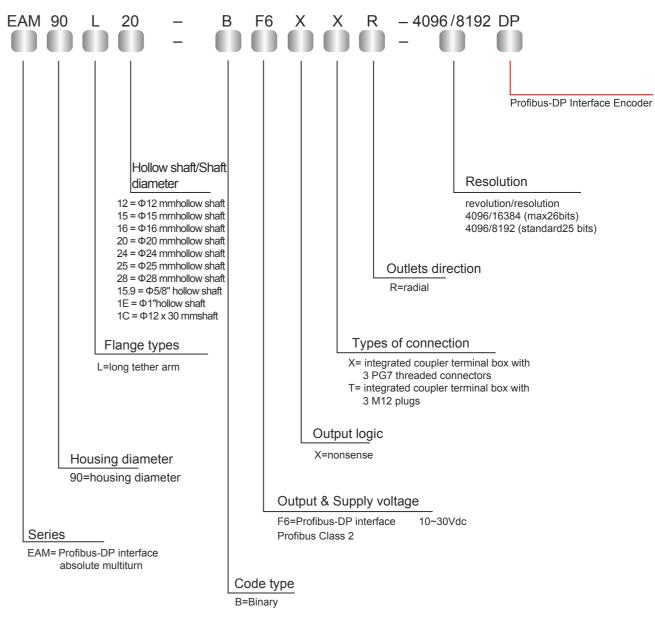
## Large Hollow Shaft Profibus-DP Interface Absolute Multiturn Encoder EAM90L

#### Dimensions(mm)



## Large Hollow Shaft Profibus-DP Interface Absolute Multiturn Encoder EAM90L

#### Order Code



Accessories Installation accessories Various types of connection



Please see the enclosed CD for GSD documents and operation manual.

## Large Hollow Shaft Absolute Multiturn Encoder EAM90L



#### Description

Large hollow shaft absolute multiturn encoder EAM90L series delivers good performance in withstanding mechanical damages and higher axial and radial loads. Its unique hollow shaft structure, various types of shafts diameters are available for different applications. It is equipped with resolution up to 16384(14 bit) and the RESET function.

#### Features

- Gray or Binary available
- Space-saver hollow shaft design, "C" ring lock
- Durable stainless steel shaft Φ12~Φ28mm
- Waterproof seal provides greater IP level
- Metal housing can withstand higher axial and radial loads.
- Resolution up to 16384
- Protection class IP65

#### Equipped with short-circuit and reverse connection protection

· Output cables or connectors are available for easy maintenance

#### **Mechanical Characteristics**

Shaft diameter (mm)	Ф12H7/Ф15H7/Ф20H7/Ф24H7/Ф28H7/
	Ф(5/8)"Н7/Ф1"Н7/Ф12g6Х30
Protection acc. to EN 60529	IP65
Speed (r/m)	6000
Max load capacity of the shaft	
axial	40N
radial	80N
Shock resistance	50G/11ms
Vibration resistance	10G 10~2000Hz
Bearing life	10 <sup>9</sup> revolution
Moment of inertia	1.8×10 <sup>-6</sup> kgm <sup>2</sup>
Starting torque	<0.1Nm max
Body material	AL-alloy
Housing material	AL-alloy
Operating temperature	-20°C~~+80°C
Storage temperature	-25°C~~+85°C
Weigh	600g
Electrical Characteristi	cs
Output circuit	SSI
Output driver	RS422
Resolution	14 Bits
Supply voltage (Vdc)	10-30V
Power consumption (no load)	≤200mA
Permissible load (channel)	±20mA
Pulse of frequency	Max. 1MHz
Signal level high	Typ. 3.8V
Signal level low	Max. 0.5V
Rise timeTr	Max 100ns
Fall timeTf	Max 100ns
Terminal Configuration	
SSI Wiring Guide	
Signal 0V +Ub +0	C -C +D -D ST* VR* 🗧

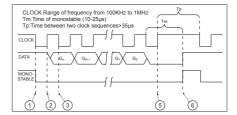
BN GN YE GY PK BU RD

8

PH

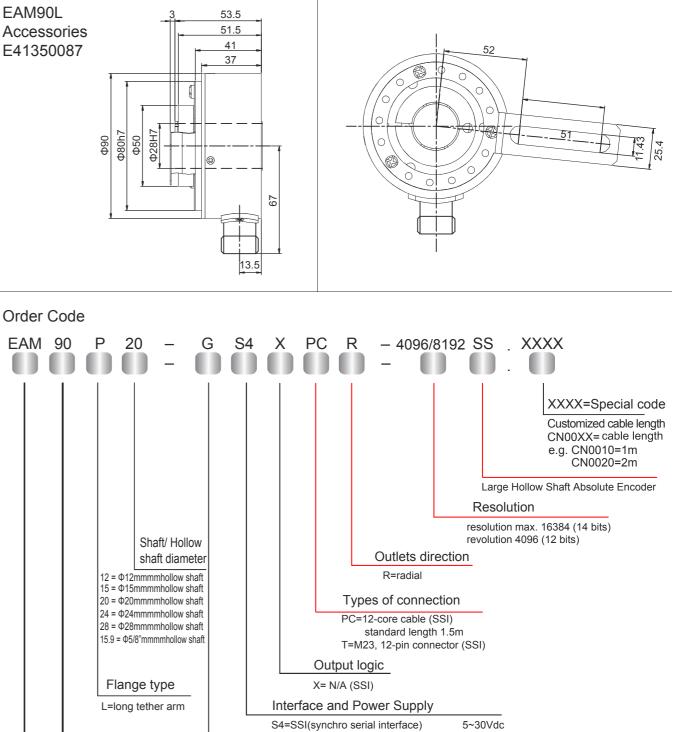
2 3 4 5 6 7

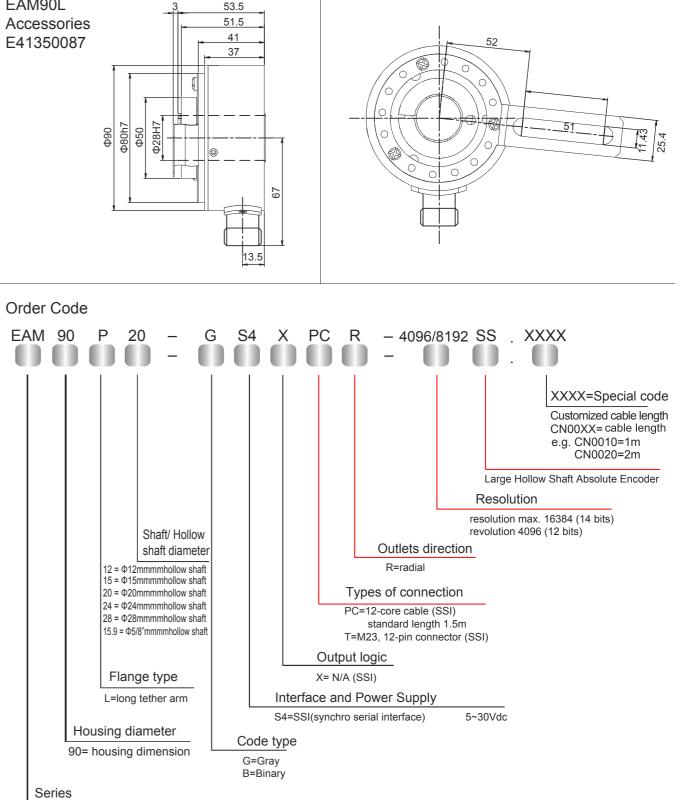
Available conventional resolution: Resolution per turn: 1024, 2048, 4096, 8192, 16384 Number of turns: 1024, 2048, 4096, 8192



## Large Hollow Shaft Absolute Multiturn Encoder EAM90L

#### Dimensions





EAM=standard absolute multiturn

Color

12-pin

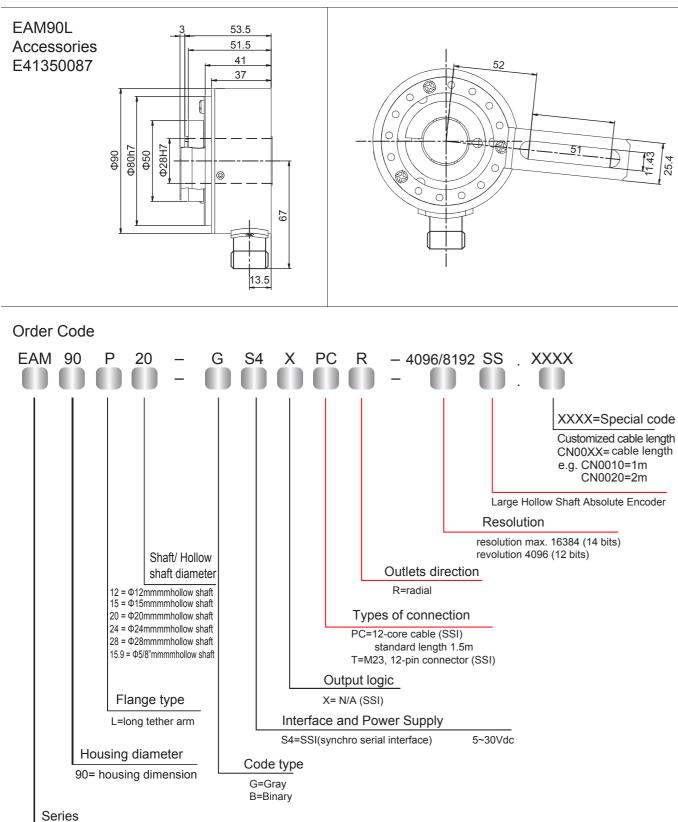
WH

1



## Large Hollow Shaft Absolute Multiturn Encoder EAM90L

#### Dimensions



EAM=standard absolute multiturn



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